

Errata for the paper entitled

“Second-order stagewise backpropagation for Hessian-matrix analyses and investigation of negative curvature”

by Eiji Mizutani and Stuart E. Dreyfus.

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As of **July 27, 2008.**

- (1) **Page 194:** In Eq.(4), θ^s should be $\theta^{s,s+1}$, and add “=” (notation for being equal to) between \mathbf{G}^s and $\mathbf{y}_+^s \delta^{s+1^T}$.
(2) **Page 195:** Eq.(5) should be expressed for recursion as

$$\underbrace{\mathbf{Z}^s}_{P_s \times P_s} = \underbrace{\mathbf{N}^{s,s+1^T}}_{P_s \times P_{s+1}} \underbrace{\mathbf{Z}^{s+1}}_{P_{s+1} \times P_{s+1}} + \underbrace{\left\langle \left[\frac{\partial^2 \mathbf{y}^s}{\partial \mathbf{x}^s \partial \mathbf{x}^s} \right], \boldsymbol{\xi}^s \right\rangle}_{P_s \times P_s},$$

where all the notations are defined in the paper except a matrix \mathbf{N} below

$$\underbrace{\mathbf{N}^{s,s+1}}_{P_{s+1} \times P_s} \stackrel{\text{def}}{=} \left[\frac{\partial \mathbf{x}^{s+1}}{\partial \mathbf{x}^s} \right] = \boldsymbol{\Theta}_{\text{void}}^{s,s+1} \left[\frac{\partial \mathbf{y}^s}{\partial \mathbf{x}^s} \right].$$

The above recurrence relation is the same as Eq.(13) in Mizutani, Dreyfus, & Demmel (2005); see also Eq.(27) in Mizutani & Dreyfus, 2006.

- (3) **Page 195:** In Eqs.(10) and (11), θ^s should be $\theta^{s,s+1}$; likewise, θ^r should be $\theta^{r,r+1}$.
(4) **Page 197:** Just above Eq.(14), the sentence

In general, the residual Hessian matrix \mathbf{S} in \mathbf{H} can separate into two types of blocks should read

In general, the residual Hessian matrix \mathbf{S} in \mathbf{H} always includes two types of blocks

- (5) **Page 197:** Eq.(16) should have included an additional matrix \mathbf{T} for a general expression as

$$\mathbf{S} = \begin{bmatrix} \underbrace{\mathbf{V}^3}_{n_3 \times n_3} & & \\ & \underbrace{\mathbf{V}^2}_{n_2 \times n_2} & \\ & & \underbrace{\mathbf{V}^1}_{n_1 \times n_1} \end{bmatrix} + \begin{bmatrix} & \underbrace{\boldsymbol{\Gamma}^{2,3^T}}_{n_2 \times n_3} & \underbrace{\boldsymbol{\Gamma}^{1,3^T}}_{n_1 \times n_3} \\ \underbrace{\boldsymbol{\Gamma}^{2,3}}_{n_2 \times n_3} & & \underbrace{\boldsymbol{\Gamma}^{1,2^T}}_{n_1 \times n_2} \\ \underbrace{\boldsymbol{\Gamma}^{1,3}}_{n_1 \times n_3} & \underbrace{\boldsymbol{\Gamma}^{1,2}}_{n_1 \times n_2} & \end{bmatrix} + \mathbf{T},$$

where \mathbf{T} denotes all the remaining terms; see Eqs.(22) and (23) in Mizutani, Dreyfus, & Demmel (2005) for such terms that construct \mathbf{T} . See also Mizutani 2008.

- (6) **Page 201:** In Section 5, the second sentence

In MLP-learning, special sparsity structure inevitably arises in \mathbf{S} , should read

In single-hidden-layer linear-output MLP-learning, special sparsity structure inevitably arises in \mathbf{S} (e.g., see \mathbf{S} in Proof of Lemma 2),

References:

- Mizutani, E., Dreyfus, S. E., & Demmel, J. W. (2005). Second-order backpropagation algorithms for a stagewise-partitioned separable Hessian matrix. In *Proceedings of the INNS-IEEE International Joint Conference on Neural Networks* (pages 1027–1032) Vol.2.
- Mizutani, E., & Dreyfus, S.E. (2006). On derivation of stagewise second-order backpropagation by invariant imbedding for multi-stage neural-network learning. In *Proceedings of the IEEE-INNS International Joint Conf. on Neural Networks (IJCNN'06)* (pages 4762–4769).
- Mizutani, E. (2008). A tutorial on stagewise backpropagation for efficient gradient and Hessian evaluations. To appear in *Proceedings of the 2008 Joint 4th International Conference on Soft Computing and Intelligent Systems and 9th International Symposium on advanced Intelligent Systems (SCIS & ISIS 2008)*, (invited paper), Nagoaya, JAPAN, 2008.

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