# IEOR 265 – Lecture 8 Nadaraya-Watson

# 1 Small Denominators in Nadaraya-Watson

The denominator of the Nadaraya-Watson estimator is worth examining. Define

$$\hat{g}(x_0) = \frac{1}{nh^p} \sum_{i=1}^n K(||x_i - x_0||/h),$$

and note that  $\hat{g}(x_0)$  is an estimate of the probability density function of  $x_i$  at the point  $x_0$ . This is known as a kernel density estimate (KDE), and the intuition is that this is a smooth version of a histogram of the  $x_i$ .

The denominator of the Nadaraya-Watson estimator is a random variable, and technical problems occur when this denominator is small. This can be visualized graphically. The traditional approach to dealing with this is *trimming*, in which small denominators are eliminated. The trimmed version of the Nadaraya-Watson estimator is

$$\hat{\beta}_0[x_0] = \begin{cases} \frac{\sum_{i=1}^n K(\|x_i - x_0\|/h) \cdot y_i}{\sum_{i=1}^n K(\|x_i - x_0\|/h)}, & \text{if } \sum_{i=1}^n K(\|x_i - x_0\|/h) > \mu\\ 0, & \text{otherwise} \end{cases}$$

. One disadvantage of this approach is that if we think of  $\hat{\beta}_0[x_0]$  as a function of  $x_0$ , then this function is not differentiable in  $x_0$ .

#### 2 L2-Regularized Nadaraya-Watson Estimator

A new approach is to define the L2-regularized Nadaraya-Watson estimator

$$\hat{\beta}_0[x_0] = \frac{\sum_{i=1}^n K(\|x_i - x_0\|/h) \cdot y_i}{\lambda + \sum_{i=1}^n K(\|x_i - x_0\|/h)},$$

where  $\lambda > 0$ . If the kernel function is differentiable, then the function  $\hat{\beta}[x_0]$  is always differentiable in  $x_0$ .

The reason for this name is that under the M-estimator interpretation of Nadaraya-Watson estimator, we have that

$$\hat{\beta}[x_0] = \arg\min_{\beta_0} \|W_h^{1/2}(Y - 1_n\beta_0)\|_2^2 + \lambda \|\beta_0\|_2^2 = \arg\min_{\beta_0} \sum_{i=1}^n K(\|x_i - x_0\|/h) \cdot (y_i - \beta_0)^2 + \lambda \beta_0^2.$$

Lastly, note that we can also interpret this estimator as the mean with weights

$$\{\lambda, K(||x_1 - x_0||/h), \dots, K(||x_n - x_0||/h)\}$$

of points  $\{0, y_1, ..., y_n\}$ .

## 3 Partially Linear Model

Recall the following partially linear model

$$y_i = x'_i\beta + g(z_i) + \epsilon_i = f(x_i, z_i; \beta) + \epsilon_i,$$

where  $y_i \in \mathbb{R}, x_i, \beta \in \mathbb{R}^p, z_i \in \mathbb{R}^q, g(\cdot)$  is an unknown nonlinear function, and  $\epsilon_i$  are noise. The data  $x_i, z_i$  are i.i.d., and the noise has conditionally zero mean  $\mathbb{E}[\epsilon_i | x_i, z_i] = 0$  with unknown and bounded conditional variance  $\mathbb{E}[\epsilon_i^2 | x_i, z_i] = \sigma^2(x_i, z_i)$ . This model is known as a partially linear model because it consists of a (parametric) linear part  $x'_i\beta$  and a nonparametric part  $g(z_i)$ . One can think of the  $g(\cdot)$  as an infinite-dimensional nuisance parameter, but in some situations this function can be of interest.

#### 4 Nonparametric Approach

Suppose we were to compute a LLR of this model at an arbitrary point  $x_0$ ,  $z_0$  within the support of the  $x_i, z_i$ :

$$\begin{bmatrix} \hat{\beta}_0[x_0, z_0] \\ \hat{\beta}[x_0, z_0] \\ \hat{\eta}[x_0, z_0] \end{bmatrix} = \arg\min_{\beta_0, \beta, \eta} \left\| W_h^{1/2} \left( Y - \begin{bmatrix} 1_n & X_0 & Z_0 \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta \\ \eta \end{bmatrix} \right) \right\|_2^2,$$

where  $X_0 = X - x'_0 1_n$ ,  $Z_0 = Z - z'_0 1_n$ , and

$$W_{h} = \operatorname{diag}\left(K\left(\frac{1}{h} \left\| \begin{bmatrix} x_{1} \\ z_{1} \end{bmatrix} - \begin{bmatrix} x_{0} \\ z_{0} \end{bmatrix} \right\| \right), \dots, K\left(\frac{1}{h} \left\| \begin{bmatrix} x_{n} \\ z_{n} \end{bmatrix} - \begin{bmatrix} x_{0} \\ z_{0} \end{bmatrix} \right\| \right) \right).$$

By noting that  $\nabla_x f = \beta$ , one estimate of the parametric coefficients is  $\hat{\beta} = \hat{\beta}[x_0, z_0]$ . That is, in principle, we can use a purely nonparametric approach to estimate the parameters of this partially linear model. However, the rate of convergence will be  $O_p(n^{-2/(p+q+4)})$ . This is much slower than the parametric rate  $O_p(1/\sqrt{n})$ .

## 5 Semiparametric Approach

Ideally, our estimates of  $\beta$  should converge at the parametric rate  $O_p(1/\sqrt{n})$ , but the  $g(z_i)$  term causes difficulties in being able to achieve this. But if we could somehow subtract out

this term, then we would be able to estimate  $\beta$  at the parametric rate. This is the intuition behind the semiparametric approach. Observe that

$$\mathbb{E}[y_i|z_i] = \mathbb{E}[x_i'\beta + g(z_i) + \epsilon_i|z_i] = \mathbb{E}[x_i|z_i]'\beta + g(z_i),$$

and so

$$y_i - \mathbb{E}[y_i|z_i] = (x_i'\beta + g(z_i) + \epsilon_i) - \mathbb{E}[x_i|z_i]'\beta - g(z_i) = (x_i - \mathbb{E}[x_i|z_i])'\beta + \epsilon_i.$$

Now if we define

$$\hat{Y} = \begin{bmatrix} \mathbb{E}[y_1|z_1] \\ \vdots \\ \mathbb{E}[y_n|z_n] \end{bmatrix}$$
$$\hat{X} = \begin{bmatrix} \mathbb{E}[x_1|z_1]' \\ \vdots \\ \mathbb{E}[x_n|z_n]' \end{bmatrix}$$

and

then we can define an estimator

$$\hat{\beta} = \arg\min_{\beta} \|(Y - \hat{Y}) - (X - \hat{X})\beta\|_2^2 = ((X - \hat{X})'(X - \hat{X}))^{-1}((X - \hat{X})'(Y - \hat{Y})).$$

The only question is how can we compute  $\mathbb{E}[x_i|z_i]$  and  $\mathbb{E}[y_i|z_i]$ ? It turns out that if we compute those values with the trimmed version of the Nadaraya-Watson estimator, then the estimate  $\hat{\beta}$  converges at the parametric rate under reasonable technical conditions. Intuitively, we would expect that we could alternatively use the *L*2-regularized Nadaraya-Watson estimator, but this has not yet been proven to be the case.