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# Single and Multisettlement Approaches to Market Clearing Under Demand Uncertainty 

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#### Abstract

Participants in electricity markets face a substantial amount of uncertainty, and with increased penetration of volatile renewable generation this uncertainty has further increased. Conventionally designed electricity markets cope with uncertainty by running two markets: a market that is cleared ahead of time, followed by a real-time balancing market to reconcile actual realizations of demand and available generation. In such mechanisms, the initial clearing process does not take into account the distribution of outcomes in the balancing market. Recently, an alternative so-called stochastic settlement market has been proposed (see, e.g., Pritchard et al. 2010 [Pritchard G, Zakeri G, Philpott A (2010) A single-settlement, energy-only electric power market for unpredictable and intermittent participants. Oper. Res. 58(4):1210-1219.] and Bouffard et al. 2005 [Bouffard F, Galiana FD, Conejo AJ (2005) Market-clearing with stochastic security-Part I: Formulation. IEEE Trans. Power Systems 20(4):1818-1826.]) where the ISO clears both stages in one single settlement market.

While the effectiveness of the stochastic market clearing mechanism is clear when the market is competitive, this is open to question for imperfectly competitive markets. In this paper we consider simplified models for two types of market clearing mechanisms. First, a market clearing mechanism utilized in New Zealand, whereby firms offer in advance and are notified of a clearing quantity and price guide based on an estimate of demand, followed by real-time dispatch. We refer to this as NZTS. Secondly we consider a simplified stochastic programming market clearing mechanism. We compute Nash equilibria of games resulting from each of the market clearing mechanisms. We prove that under the assumption of symmetry, our simplified stochastic programming market clearing is equivalent to a two-period single settlement system that takes account of deviation penalties in the second stage. These, however, differ from NZTS. We show that when we assume symmetry, this stochastic settlement model results in better social welfare than does NZTS. We also investigate a number of asymmetric examples numerically.


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Keywords: uncertainty • stochastic programming • electricity markets • equilibrium • market clearing

## 1. Introduction

Electricity markets face two key features that set them apart from other markets. The first is that electricity cannot be stored, so demand must equal supply at all times. This necessitates the presence of a real-time (or balancing) market, although it is also imperative that a day-ahead market clears to cater for the participation of slower response units.
Second, electricity is transported from suppliers to load over a transmission network with possible constraints. The combination of these two features means that in almost all electricity markets today, an independent system operator (ISO) sets dispatch centrally and clears the market. Generators and demand-side users can make offers and bids, and the ISO will choose which are accepted according to a predetermined settlement system.

The conventional arrangement of a day-ahead followed by real-time market clearing takes on different nuances in various jurisdictions. One approach used is to run a two-period market clearing model (see, e.g., Kamat and Oren 2004). In many jurisdictions such as the PJM, this amounts to a day-ahead followed by a real-time market with separate, financially binding settlements for each market (see Ott 2003, Zheng and Litvinov 2006). Here, generating firms bid in supply function offers of generation and the utilities (or load serving entities) bids demand functions in the day-ahead market. The market is cleared without participation from volatile renewable generation such as wind. Then in real time firms compete for any deviations introduced in the spot through wind generation, with possibly updated supply and demand functions. We note that almost all such markets are
strictly monitored to ensure participants reflect their true cost of generation.

In New Zealand, however, the nature of the market is somewhat different. The New Zealand electricity market (NZEM) is a hydro-dominated market. As it is difficult to obtain an accurate value of water, it is not possible to monitor the NZEM to ensure that generators bid at cost. In the NZEM, generators can place offers for a given half hour period up to "gate closure," which occurs two hours prior to the designated period. At gate closure these offers are locked in. Estimates of dispatch quantity and price are provided to the industry participants based on forecast demand in the periods leading up to real time. We refer to these as predispatch quantities and prices. ${ }^{1}$

At the start of the designated period an accurate measure of demand is available to the ISO and the generators are dispatched accordingly. In the NZEM, the ISO redispatches the generators every five minutes during a half hour period, using updated demand information but according to the same offer curves, locked in at gate closure. ${ }^{2}$ In the NZEM there is only a single settlement, as the predispatch quantities and prices are not financially binding. In this two-period singlesettlement (NZTS) market, expected demand is used to clear the predispatch quantities and the ISO has no explicit measure of any deviation costs for a generator. Here, the nature of the supply function (different quantities offered at different prices) is relied upon to allow firms to cope with different dispatch levels. While this may have been adequate in systems with limited uncertainty, growing penetration of renewables can lead to large deviations in dispatch at gate closure versus real time. These short-term changes will have associated costs that are not built into a supply function, which operates on the principle that demand may vary but the firm will have more advance warning of this (for an account of these deviation costs we refer the reader to Myles and Herron 2012 and Kumar et al. 2012). We demonstrate in this paper that it is important to reflect these deviation costs in terms of social welfare. This is relevant to some recent debates on complexity versus simplification in electricity markets (see Bushnell 2013).

An alternative to the two-period settlement systems is to use a stochastic settlement process to deal with variable demand. (We will consider demand as gross demand net intermittent renewable generation such as wind, which in the NZEM is forced to offer at zero price.) In a stochastic settlement, the ISO can choose both predispatch and short-run deviations for each generator to maximize expected social welfare in one step. We might then expect a stochastic settlement system to do better (on average) than a twoperiod system. The idea of a stochastic settlement can be attributed to Bouffard et al. (2005), Wong and Fuller (2007), and Pritchard et al. (2010) and is further
analyzed in Morales et al. (2012, 2014a, b), and Zavala et al. (2015). In these two-stage, single settlement models, the predispatch clears with information about the future distribution of uncertainties in the system (e.g., demand and volatile renewable generation) and information about deviation costs for each generator. These models assume that each firms' offers and deviation costs are truthful. In an imperfectly competitive market (where suppliers may offer generation above cost) this assumption is not valid. Can the stochastic settlement auction give better expected social welfare when firms are behaving strategically? This is the question explored in this paper.

To answer this question, we should first construct an equilibrium model of these two market mechanisms. There are many studies that develop equilibrium models for energy and other markets. These include the seminal work of Klemperer and Meyer (1989) that analyzes supply function equilibrium models, as well as various Cournot and linear supply function equilibrium models such as those developed in Downward et al. (2010), Green (1999), Baldick et al. (2004), and Day et al. (2002).

These studies focus on a market with a single settlement. For our investigations, it is necessary to build equilibria over markets with a predispatch followed by balancing clearing, such as the NZTS. Studies that address equilibria obtained on a forward (contract) market followed by a wholesale market yield models that in their two-stage nature are relevant to our analysis. These include Allaz (1992), Allaz and Vila (1993), Willems (2005), and supply function equilibrium models with a preceding contract stage such as Newbery (1998), Anderson and Xu (2005), Gans et al. (1998), as well as Haskel and Powell (1994), Willems (2005), Bushnell (2007), and Su (2007). Our focus for NZTS however is to address the effect of costs (to the generators) due to deviations from dispatch point, resulting from short-term (a few trading periods) variations in net demand. This has not been studied in any of the previous papers.

There are also a number of models in the literature that consider uncertainty in conjunction with forward markets. von der Fehr and Harbord (1992) explained how spot prices could be reduced as an effect of contract forward markets. Shanbhag (2006) investigated a two settlement stochastic market for a twonode network using a Nash-Cournot equilibria. Zhang et al. (2010) proposed a two-stage oligopoly stochastic Nash-Cournot equilibrium problem with equilibrium constraints. None of these models however cater for the recently proposed stochastic programming market clearing mechanism that we investigate in this paper.

## Our Contribution

In this paper, we investigate the effects of using a stochastic market clearing mechanism that considers
deviation costs and uncertainty instead of the existing deterministic mechanisms (such as New Zealand electricity market). In particular, we define three models, which we analyze as games. We derive the Nash equilibria of these models, and use them to compare the performance of these models:

1. A two-period settlement model (in particular, a simplified version of the New Zealand electricity market) representing a deterministic market clearing mechanism.
2. A single settlement stochastic programming mechanism with deviation costs as part of the offer submitted by the generating firms.
3. A single settlement stochastic programming mechanism with constant deviation penalties.

We start by introducing a simplified version of the NZTS market currently operated in New Zealand. We will then introduce a simplified version of the stochastic programming mechanism for clearing electricity markets. The first simplification in our models is to use affine supply function offers following the work of Green $(1996,1999)$. He used this restricted form of supply function to assess the effects of policies on enhancing competition in the England and Wales market. He showed that in presence of linear demand functions, it is always possible to find a supply function equilibrium that is an equilibrium over affine supply functions. The linear nature of these supply functions assists us in obtaining a tractable analytical solution. Subsequently, Baldick et al. (2004) extended Green's work to piecewise linear supply functions. Day et al. have also used linear supply functions but with specific forms of conjectural variation (see Day et al. 2002).

In what follows, we will present existence results for equilibria for the simplified NZTS and derive an analytical expression for a symmetric equilibrium (with identical firms). We then establish the key result that reduces our simplified stochastic market clearing mechanism (ISOSP) to a NZTS type model, but with explicit deviation penalties. Here again we construct analytical expressions for symmetric equilibria, for each level of deviation penalty. Finally we compare the symmetric equilibria of NZTS and a special case of ISOSP settlements and show that the ISOSP settlement with fixed, explicit deviation costs performs better in terms of expected social welfare for a large range of deviation penalties that includes the true deviation costs common to the identical firms. When the assumption of symmetry is relaxed, analytical expressions for an equilibrium become intractable for either model. We will therefore present numerical results for a number of cases and compare equilibria of the two market clearing systems. We find that in all cases ISOSP performs better than the NZTS.

In Section 6.2, we repeat the symmetric experiments that construct and compare the equilibria of NZTS and

ISOSP mechanisms, but for the restricted version of linear supply functions where the intercept is set to zero. Here we find that there is a unique symmetric equilibrium for the game. For this case, we present an example where the ISOSP welfare is in fact less than the NZTS mechanism. This result is in contrast to the previous set of results where generators have another degree of freedom in their bids in the form of an intercept.

In summary, our contributions to this paper include the following.

- We present a mathematical model for each of the three market mechanisms. We prove the existence of Nash equilibria and derive analytical expressions of the equilibria for symmetric firms.
- We show that the stochastic settlement mechanism with fixed deviation penalties can outperform the NZTS model given that the deviation penalty is chosen appropriately, i.e., in a (large) interval that includes the true deviation costs.
- To investigate the asymmetric case, through an iterative process, we compute the equilibria of the models numerically. Again, the stochastic settlement outperforms the NZTS model.
- We investigate a special case of stochastic settlement with zero intercepts. We find the unique equilibrium and show that the previous conclusion cannot be extended to this restricted version of ISOSP.


## 2. The Market Environment

In this paper, we aim to compare different market designs for electricity. We begin by presenting assumptions that are common to all markets we consider, features of what we call the market environment. These include such considerations as the number of firms, the costs firms face, the structure of demand, and so forth.

Assumption 1. The market environment may be defined by the following features.

- Electricity is traded over a network with no transmission constraints and no line losses, thus we may consider all trading as taking place at a single node.
- Demand for electricity is uncertain, and may realize in one of $s \in\{1, \ldots, S\}$ possible outcomes (scenarios), each with probability $\theta_{s}$. Demand in state $s$ is assumed to be linear, and defined by the inverse demand function $p_{s}=Y_{s}-$ $Z C_{s}$, where $C_{s}$ is the quantity of electricity and $p_{s}$ is the market price, in scenario s, and Z is the slope that indicates the rate of change of price as a function of quantity $C_{s}$; all scenarios have the same slope. Without loss of generality, assume $Y_{1}<Y_{2}<\cdots<Y_{S}$. We will denote the expected value of $Y_{s}$ by $Y=\sum_{s} \theta_{s} Y_{s}$. The distribution of demand is common knowledge to all agents.
- There are $n$ identical firms wishing to sell electricity.
- For a given firm $i$ in scenario s, we will denote the predispatch quantity by $q_{i}$, and any short-run change in production by $x_{i, s}$. Variable $q_{i}$ is a "here and now" decision
made by the ISO and $x_{i, s}$ is a "wait and see" decision to adjust production to meet demand. Thus a generator's actual production in scenario s is equal to $q_{i}+x_{i, s}$, which we denote by $y_{i, s}$.
- To produce $y_{i, s}$, firm $i$ will incur a cost of production given by $\alpha\left(q_{i}+x_{i, s}\right)+(\beta / 2)\left(q_{i}+x_{i, s}\right)^{2}$ plus a deviation cost (from the targeted $q_{i}$ production), ( $\left.\delta / 2\right) x_{i, s}^{2}$. Here $q_{i}$ is the expected dispatch of firm $i$, and $q_{i}+x_{i, s}$ is the actual shortrun dispatch and $\delta>0$.
- As minimum marginal cost of generation should not be more than maximum price of electricity, we assume

$$
\alpha \leqslant Y_{s} \quad \forall s \in\{1, \ldots, S\} .
$$

- There is an ISO who takes bids and determines dispatch and prices according to the given market design.
- All agents have full information about costs and the distribution of demand (scenarios and probabilities).
- We assume that the strategy space of each participant is defined by their choice of linear supply function parameters discussed under each market clearing mechanism.

Our assumptions on generators' cost functions are particularly critical to the analysis that follows, and deserve further explanation. Generators face two distinct costs when generating electricity. If given sufficient advance notice of the quantity they are to dispatch, the generator can plan the allocation of turbines to produce that quantity most efficiently. This is what we mean by a long-run cost function. The interpretation of this is the lowest possible cost at which a generator can produce quantity $q$. In electricity markets, however, demand fluctuates at short notice, and the ISO may ask a generator to change its dispatch at short notice. In this case, generators may not have enough time to efficiently reallocate their turbines. For example, many thermal turbines take hours to ramp-up. Most likely, the generator will have to adopt a less efficient production method, such as running some turbines above their rated capacity, which also increases the wear on the turbines. Thus there is some inherent cost in deviating from an expected predispatch in the short-run. This cost can be incurred even if the requested deviation is negative. We assume that the generator will be unable to revert to the most efficient mode of producing this quantity $q_{i}+x_{i, s}$ in the short-run, so it pays a penalty cost. Note that this imposes a positive penalty cost upon the generator for making the shortrun change, even if the change is negative. This penalty cost is additively imposed on top of the "efficient" cost of producing at the new level. We call this cost the deviation cost. Note that we assume the symmetric case in which cost of generation and deviation is determined through the same constant parameters $(\alpha, \beta, \delta)$.

Our goal is to compare the outcomes of different markets imposed upon this environment. To be able to draw comparisons in different paradigms, we need
to examine the steady state behaviour of participants under the different market clearing mechanisms. To this end, we need to compute equilibria arising under the different market clearing mechanisms. To make the computations tractable, we will restrict the firms to offer linear supply functions in the following sections of this paper.

## 3. Two-Period Settlement (NZTS) Model

In this section, we will introduce a two-period market that is inspired by the market clearing mechanism as it operates currently in New Zealand. As explained in the introduction, in the NZEM firms bid a step supply function for a given half hour period. The bid is made at least two hours in advance. Once gate closure occurs (two hours in advance of any given period), the supply function offers can not be changed. (This is at least in part because of the fact that there is no capacity market in the NZEM and the system operator may be faced with a real possibility of curtailing demand if the generators were to change their bids in real time.) The market will then be cleared six times, every five minutes during the given half-hour period. Each five-minute redispatch is computed with real-time demand, but with the supply offer stacks that have been submitted prior to gate closure. ${ }^{3}$ We simplify the situation by assuming the market clears only twice; once after the offers are submitted, but before demand is realized. We call this the "predispatch" phase, which tells the generators approximately how much they should produce. Once demand is realized, the same offers will be used to determine actual dispatch in what we call the "spot settlement." The difference between predispatch and spot dispatch is a generator's short-run deviation, which is subject to potentially higher costs as we described earlier. However, the ISO has no knowledge of this cost and it is not explicitly stated in the generators' bids. This cost can be indirectly reflected in the supply functions the generators bid in.

### 3.1. Mathematical Model

Our simplified model for the NZTS market has two distinct stages: predispatch and spot. Following the large body of literature on affine supply functions (see, e.g., Green 1996, Baldick et al. 2004) we will work with a linear demand curve and frame generator supply offers as linear functions. Explicitly, each generator $i$ bids a supply function $a_{i}+b_{i} q_{i}$ before the predispatch market to represent their quadratic costs. This supply function is required to be increasing, i.e., the offered $b_{i}$ must satisfy $b_{i} \geqslant \varepsilon>0$, where $\varepsilon$ is the machine accuracy. ${ }^{4}$ Note that unlike (Green 1996), we do not assume that the intercept $a_{i}=0$. Following our main analysis, we briefly present a special case where $a_{i}=0$ is required.

When generators lock in their offers, demand is uncertain (in New Zealand this point in time is referred
to as gate closure). The ISO will then use the generator's bid twice: once to clear the predispatch market, and once again after demand is realized to clear the spot market. As in reality, in both the predispatch and spot markets, the ISO aims to maximize social welfare, assuming generators are bidding their true cost functions. Since demand is unknown in predispatch, the ISO will nominate (and use) an expected demand (and will not consider the distribution of demand):

$$
\begin{gather*}
\min _{q_{i}, i \in\{1, \ldots, n\}} z, \quad z=\sum_{i=1}^{n}\left[\left(a_{i} q_{i}+\frac{b_{i}}{2} q_{i}^{2}\right)-\left(Y Q-\frac{Z}{2} Q^{2}\right)\right] \\
\text { s.t. } \quad \sum_{i=1}^{n} q_{i}-Q=0 \quad[f] . \tag{1}
\end{gather*}
$$

From this first settlement, the ISO can extract a forward price $f$ equal to the shadow price on the (expected demand balance) constraint. $f$ is not used for any settlements as the predispatch quantity and prices are merely a guide at this stage. Recall that the predispatch quantity for generator $i$ is denoted by $q_{i}$. After predispatch is determined, true demand is realized, and the ISO then clears the spot market (using the specific demand scenario that has been realized) to maximize welfare by solving (2):

$$
\begin{align*}
& \min _{y_{i, s}} z, \quad z=\sum_{i=1}^{n}\left[\left(a_{i} y_{i, s}+\frac{b_{i}}{2} y_{i, s}^{2}\right)-\left(Y_{s} C_{s}-\frac{Z}{2} C_{s}^{2}\right)\right] \\
& \text { s.t. } \sum_{i=1}^{n} y_{i, s}-C_{s}=0 \quad\left[p_{s}\right] . \tag{2}
\end{align*}
$$

Here again the ISO computes a spot price $p_{s}$ as the shadow price on the constraint. (Note that we can eliminate the constraint and substitute $C_{s}$ in the objective, however, imposing this constraint enables the easy introduction of the price as the shadow price attached to the constraint.) The generator is not permitted to change its bid after predispatch, but does face an additional deviation cost $\delta$ for its short-run deviation.

Note that in both ISO optimization problems (1)-(2) we have dispensed with nonnegativity constraints on the predispatch and dispatch quantity both, following the convention of supply function equilibrium models (see, e.g., Klemperer and Meyer 1989, Bolle 1992), in order to enable the analytic computation of equilibria. We will demonstrate that the resulting symmetric equilibria of our NZTS market model will always have associated nonnegative predispatch and dispatch quantities.

Firm $i$ 's profit in scenario $s$ in this market is then given by
$u_{i, s}\left(q_{i}, y_{i, s}\right)=p_{s} y_{i, s}-\left(\alpha y_{i, s}+\frac{\beta}{2} y_{i, s}^{2}+\frac{\delta}{2}\left(y_{i, s}-q_{i}\right)^{2}\right)$.
3.2. Equilibrium Analysis of the Two-Period Market In this section, we will present equilibria of the NZTS market model. We will first compute the optimal dispatch quantities from the ISO's optimal dispatch problems (1) and (2) for any number of players. We will then embed these quantities in each generator's expected profit function and allow the generators to simultaneously optimize over their (linear) supply function parameters to obtain equilibrium offers.

Proposition 1. Problem (1) is a convex program with a strictly convex objective. Its unique optimal solution and the corresponding optimal dual $f$ are given by

$$
f=\frac{Y+Z A}{Z B+1}, \quad q_{i}=f B_{i}-A_{i}
$$

where $A_{i}=a_{i} / b_{i}, B_{i}=1 / b_{i}, A=\sum_{i=1}^{n} A_{i}$ and $B=\sum_{i=1}^{n} B_{i}$.
Proof. Note that problem (1) has a single linear constraint and that its objective is a strictly convex quadratic as we have assumed that $b_{i}>0$ and $Z>0$. The problem therefore has a unique optimal solution delivered by the first-order conditions provided below:

$$
\begin{gather*}
Q-\sum_{i=1}^{n} q_{i}=0  \tag{4}\\
f-Y+Z Q=0  \tag{5}\\
-f+a_{i}+b_{i} q_{i}=0 \quad i \in\{1,2, \ldots, n\} \tag{6}
\end{gather*}
$$

Algebraic manipulation of Equations (5)-(6) will provide the results.

We note that Proposition 1 (and the next proposition) are similar to analysis in Green $(1996,1999)$, although we allow for an intercept parameter in our model.

Proposition 2. For each scenario s, problem (2) is a convex program with a strictly convex objective. Its unique optimal solution and the corresponding optimal dual $p_{s}$ are given by

$$
p_{s}=\frac{Y_{s}+Z A}{Z B+1}, \quad y_{i, s}=p_{s} B_{i}-A_{i}
$$

where $A_{i}, B_{i}, A$, and $B$ are defined in Proposition 1.
Proof. Problems (2) and (1) are structurally identical, therefore the simple proof of Proposition (1) applies again here.

Remark 1. Note from the above that the predispatch price (and quantity) are equal to the expected spot market prices (and quantities, respectively). That is,

$$
\begin{equation*}
f=\sum_{s=1}^{S} \theta_{s} p_{s} . \tag{7}
\end{equation*}
$$

We will now compute the linear supply functions resulting from the equilibrium of the TS market game laid out in (1).
3.2.1. Firm $i$ 's Computations. In this section we will focus on firm $i$ 's expected profit function. Note that using Equation (7) we obtain

$$
\begin{aligned}
u_{i} & =E_{s}\left[u_{i, s}\right] \\
& =\sum_{s=1}^{s} \theta_{s}\left(p_{s} y_{i, s}-\left(\alpha y_{i, s}+\frac{\beta}{2} y_{i, s}^{2}+\frac{\delta}{2}\left(y_{i, s}-q_{i}\right)^{2}\right)\right) .
\end{aligned}
$$

Using Propositions 1 and 2, we can rewrite $u_{i}$ as a function of $a_{i}$ and $b_{i}$. To find a maximum of $u_{i}$ (for a fixed set of competitor offers) we appeal to a transformation that will yield concavity results for $u_{i}$. We consider $u_{i}$ to be a function of $A_{i}$ and $B_{i}$ (instead of $a_{i}$ and $b_{i}$ ). Note that the transformation $\left(A_{i}=a_{i} / b_{i}, B_{i}=1 / b_{i}\right)$ is a one-to-one transformation.

Proposition 3. Let all competitor (linear) supply function offers be fixed. The following maximizes $u_{i}$ (and is therefore firm i's best response):

$$
\begin{gathered}
B_{i}=\frac{1+Z B_{-i}}{Z+\beta+\delta+Z(\beta+\delta) B_{-i}} \\
A_{i}=\frac{\alpha+B_{i}\left(Z \alpha-\delta\left(Y+Z A_{-i}\right)\right)+Z \alpha B_{-i}}{2 Z+\beta+Z \beta B_{-i}}
\end{gathered}
$$

where $A_{-i}=\sum_{j \neq i} A_{j}$ and $B_{-i}=\sum_{j \neq i} B_{j}$.
Proof. We can show that $u_{i}$ is a concave function of $A_{i}$, assuming $B_{i}$ is a fixed parameter. Here we have dispensed with the expression for $u_{i}$ as a function of $A_{i}$ and $B_{i}$ as it is long and rather complicated. We note that $u_{i}$ is a smooth function of $A_{i}$ and $B_{i}$ and that

$$
\frac{\partial^{2} u_{i}}{\partial A_{i}^{2}}=-\frac{\left(1+Z B_{-i}\right)\left(2 Z+\beta+Z \beta B_{-i}\right)}{(1+Z B)^{2}} \leqslant 0
$$

Let $B_{i}$ be arbitrary but fixed. As $u_{i}$ is a concave function of $A_{i}$ the first-order condition yields an expression for $A_{i}^{*}\left(B_{i}\right)$, the value of $A_{i}$ that maximizes $u_{i}$ (for the fixed $B_{i}$ ):

$$
\begin{aligned}
A_{i}^{*}\left(B_{i}\right)= & {\left[\left(1+Z B_{-i}\right)\left(-Y+\alpha-\mathrm{Z} A_{-i}+\mathrm{Z} \alpha B_{-i}\right)\right.} \\
& +B_{i}\left(\mathrm{Z}\left(Y+\mathrm{Z} A_{-i}\right)+\left(\mathrm{Z} \alpha+\beta Y+\mathrm{Z} \beta A_{-i}\right)\right. \\
& \left.\left.\cdot\left(Z B_{-i}+1\right)\right)\right] \cdot\left[\left(1+\mathrm{Z} B_{-i}\right)\left(2 Z+\beta+\mathrm{Z} \beta B_{-i}\right)\right]^{-1}
\end{aligned}
$$

We can embed $A_{i}^{*}\left(B_{i}\right)$ into $u_{i}$ and find the maximizer in terms of $B_{i}$. This is enough to demonstrate that the end result delivers the maximum of $u_{i}$.

After embedding this value of $A_{i}^{*}$ into the profit function, the derivative with respect to $B_{i}$ of $u_{i}$ is

$$
\frac{\partial u_{i}}{\partial B_{i}}=\frac{\left(Y^{2}-\sum_{s} \theta_{s} Y_{s}^{2}\right)\left(-1+(Z+\beta+\delta) B_{i}+Z\left(-1+(\beta+\delta) B_{i}\right) B_{-i}\right)}{(1+Z B)^{3}} .
$$

The zero of this derivative is $B_{i}^{*}=\left(1+Z B_{-i}\right) /$ $\left(Z+\beta+\delta+Z(\beta+\delta) B_{-i}\right)$. Recall that $Y=\sum_{s} \theta_{s} Y_{s}$, therefore Jensen's inequality implies $Y^{2}-\sum_{s} \theta_{s} Y_{s}^{2} \leqslant 0$. Thus, $\partial u_{i} / \partial B_{i} \geqslant 0$, when $B_{i}<B_{i}{ }^{*}$, and $\partial u_{i} / \partial B_{i} \leqslant 0$, when
$B_{i}>B_{i}^{*}$. In other words, $u_{i}$ is a quasiconcave function of $B_{i}$ and is maximized at $B_{i}=B_{i}^{*}$.

Note that evaluating $A_{i}^{*}$ at $B_{i}^{*}$ yields

$$
A_{i}^{*}=\frac{\alpha+B_{i}\left(Z \alpha-\delta\left(Y+Z A_{-i}\right)\right)+Z \alpha B_{-i}}{2 Z+\beta+Z \beta B_{-i}} .
$$

From the above, we can obtain the equilibrium of the NZTS model by solving all best responses simultaneously. This gives the unique and symmetric solution 2S-EQM:

$$
\begin{align*}
B_{i}=2[ & -(n-2) Z+\beta+\delta \\
& \left.\quad+\sqrt{(n-2)^{2} Z^{2}+2 n Z(\beta+\delta)+(\beta+\delta)^{2}}\right]^{-1}  \tag{8}\\
A_{i}= & \frac{\alpha+(n Z \alpha-Y \delta) B_{i}}{2 Z}+\beta+(n-1) Z(\beta+\delta) B_{i} \tag{9}
\end{align*}
$$

or alternatively
2S-EQM:

$$
\begin{align*}
b_{i}= & \frac{1}{2}[-(n-2) Z+\beta+\delta \\
& \left.+\sqrt{(n-2)^{2} Z^{2}+2 n Z(\beta+\delta)+(\beta+\delta)^{2}}\right]  \tag{10}\\
a_{i}= & \frac{\alpha b_{i}+(n Z \alpha-Y \delta)}{2 Z b_{i}+\beta b_{i}+(n-1) Z(\beta+\delta)} . \tag{11}
\end{align*}
$$

As we discussed earlier, these equilibrium offers yield nonnegative predispatch and dispatch quantities. Below we formally state this result.
Proposition 4. The equilibrium predispatch and spot production quantities of the firms in the NZTS market are nonnegative, i.e., $q_{i} \geqslant 0 \forall i$, and $y_{i, s} \geqslant 0 \forall i$, s where $q_{i}$ and $y_{i, s}$ are the optimal solutions to problems (1) and (2), respectively, using the equilibrium parameters from (10) and (11).

Proof. For the proof, please consult the e-companion.

## 4. Stochastic Settlement Market

### 4.1. ISOSP Model

We now introduce the market model we will use to analyze a stochastic settlement market. As discussed in the introduction, the stochastic settlement market contains only a single stage of bidding, but the market clearing procedure takes into account the distribution of future demand when determining dispatch. The market works as follows. When the market opens, demand is uncertain. Firms are allowed to bid their "normal" cost functions (the cost of producing a given output most efficiently) and a "penalty" cost function that they would need to be paid to deviate in the shortrun. Since firms have quadratic cost functions, they can bid their true costs by submitting a linear supply function. Each firm $i$ chooses $a_{i}$ and $b_{i}$ to bid the linear supply function $a_{i}+b_{i} q$, and $d_{i}$ to bid the marginal penalty cost applied to the deviation from predispatch quantity. For a marginal deviation penalty, we look for
a function that is zero when the dispatch is not changed from the predispatch quantity, as well as positive to the right and negative to the left of the predispatch. One of the simplest forms this function can take is the linear form we have assumed. While the true marginal cost of deviation for a station may be nonlinear, it is expected to be smooth as it relates to engineering attributes such as flow of water through an aperture. Therefore to the first order, it can be approximated by a linear function. Note that as with the NZTS model, these bids $\left(a_{i}, b_{i}, d_{i}\right)$ need not be their true values $(\alpha, \beta, \delta)$. The offered $b_{i}$ is required to be positive and $d_{i}$ should be nonnegative.

After generators have placed their bids, the ISO computes the market dispatch according to the stochastic settlement model (outlined below). At this point demand is still uncertain. The ISO chooses two key variables. The first is the predispatch quantity for each firm. This is the quantity the ISO asks each firm to prepare to produce, namely, the predispatch quantities $q_{i}$ defined in Section 2. The second is the short-run deviation for generator $i$ under each scenario $s$. This deviation is the variable $x_{i, s}$ defined in Section 2, representing the adjustment made to firm $i$ 's predispatch quantity in scenario $s$. The ISO can choose both predispatch and short-run deviations simultaneously, while aiming to maximize expected social welfare. The ISO assumes that generators have bid their true costs.

In the final stage, demand is realized, and the ISO will ask generators to modify their predispatch quantity according to the short-run deviation for the particular scenario. Each generator ends up producing $q_{i}+x_{i, s}$. Two prices are calculated during the course of optimizing welfare. The first is the (shadow) price of the predispatch quantities. We will denote this by $f$. The second are the prices of each of the deviations, for each of the scenarios. We will denote these by $p_{s}$ for scenario $s$. Each generator is paid $f$ per unit for its predispatch quantity $q_{i}$, and $p_{s}$ for its deviations $x_{i, s}$. Thus in realization $s$, generator $i$ makes profit equal to
$u_{i, s}\left(q_{i}, y_{i, s}\right)=p_{s} y_{i, s}-\left(\alpha y_{i, s}+\frac{\beta}{2} y_{i, s}^{2}+\frac{\delta}{2}\left(y_{i, s}-q_{i}\right)^{2}\right)$.
The stochastic optimization problem solved by the ISO can be represented as follows. ${ }^{5}$

## ISOSP:

$$
\begin{aligned}
\min _{q_{i}, x_{i, s}} & \sum_{s=1}^{S} \theta_{s}\left(\sum _ { i = 1 } ^ { n } \left[a_{i}\left(q_{i}+x_{i, s}\right)+\left(\frac{b_{i}}{2}\right)\left(q_{i}+x_{i, s}\right)^{2}\right.\right. \\
& \left.\left.+\left(\frac{d_{i}}{2}\right) x_{i, s}^{2}\right]-\left(Y_{s} C_{s}-\left(\frac{Z}{2}\right) C_{s}^{2}\right)\right) \\
\text { s.t. } & \sum_{i} q_{i}-Q=0 \quad[f] \\
& Q+\sum_{i} x_{i, s}-C_{s}=0 \quad \forall s \in\{1, \ldots, S\} \quad\left[\theta_{s} p_{s}\right],
\end{aligned}
$$

where $Q$ and $C_{s}$ stand for the total predispatched quantity and total consumption in scenario $s$, respectively.

Note that we could have eliminated the two equality constraints. However, their dual variables inform the market prices $f$ and $p_{s}$, respectively, so for clarity we have left them in. Here $p_{s}$ is the probability adjusted shadow price for the second stage.

Note that in the ISOSP, an estimate of a future distribution is used. Khazaei et al. (2013) examine the effectiveness of ISOSP in an empirical competitive setting.

### 4.2. Characteristics of the Stochastic Optimization Problem

We begin by presenting a series of results that simplify the set of solutions to the ISOSP problem. We start by establishing technical lemmas that enable us to prove that our ISOSP is equivalent to a two-period market clearing mechanism similar to NZTS, with the essential difference that now a deviation penalty is present in the ISO's dispatch in real time. These results drastically simplify the subsequent analysis of firms' behaviour in equilibrium.

Lemma 1. In the stochastic settlement market clearing, the expected deviation of firm $i$ from predispatch quantity $q_{i}^{*}$ is zero. That is, the optimal solution to ISOSP will always satisfy

$$
\sum_{s} \theta_{s} x_{i, s}^{*}=0 .
$$

Proof. Let us assume $q_{i}^{*}$ and $x_{i, s}^{*}$ form ISOSP's optimal solution. Let us define for each $i$ and $s$ the quantity $k_{i, s}=q_{i}^{*}+x_{i, s}^{*}$, the total production of firm $i$ in scenario s. Note that $C_{s}=\sum_{i} q_{i}^{*}+\sum_{i} x_{i, s}^{*}$. Assume, on the contrary, that there exists at least one firm $j$ such that $\sum_{s} \theta_{s} x_{j, s}^{*} \neq 0$. The optimal objective value of ISOSP is then given by

$$
\begin{align*}
& \sum_{i} \sum_{s} \theta_{s}\left(a_{i} k_{i, s}+\frac{b_{i}}{2}\left(k_{i, s}\right)^{2}\right)+\sum_{i} \sum_{s} \theta_{s} \frac{d_{i}}{2}\left(x_{i, s}^{*}\right)^{2} \\
& \quad+Y_{s} \sum_{i} k_{i, s}-\frac{Z}{2}\left(\sum_{i} k_{i, s}\right)^{2} . \tag{13}
\end{align*}
$$

Note that as $\sum_{s} \theta_{s} x_{j, s}^{*} \neq 0$, the term $\sum_{i} \sum_{s} \theta_{s}\left(d_{i} / 2\right)\left(x_{i, s}^{*}\right)^{2}$ is positive. Now, for a fixed $i$ and $k_{i, s}$ given from above, consider the problem

$$
\begin{gather*}
\min _{q_{i}, x_{i, s}} \frac{d_{i}}{2} \sum_{s=1}^{S} \theta_{s} x_{i, s}^{2}  \tag{14}\\
q_{i}+x_{i, s}=k_{i, s} \quad \forall s \in\{1, \ldots, S\} .
\end{gather*}
$$

This problem clearly reduces to the univariate problem

$$
\min _{q_{i}} \sum_{s=1}^{S} \theta_{s}\left(k_{i, s}-q_{i}\right)^{2},
$$

which is optimized at

$$
q_{i}=\sum_{s=1}^{S} \theta_{s} k_{i, s}
$$

We will now construct a new optimal solution for ISOSP, with an improved objective value and hence derive a contradiction. Define $\hat{q}_{i}$ and $\hat{x}_{i, s}$ by

$$
\hat{q}_{i}= \begin{cases}q_{i}^{*}, & i \neq j \\ \sum_{s=1}^{S} \theta_{s} k_{j, s} & \text { otherwise },\end{cases}
$$

and

$$
\hat{x}_{i, s}= \begin{cases}x_{i, s^{\prime}}^{*}, & i \neq j \\ k_{j, s}-\hat{q}_{j} & \text { otherwise } .\end{cases}
$$

By definition, $\hat{q}_{i}+\hat{x}_{i, s}=q_{i}^{*}+x_{i, s}^{*}$ for all $i$ and $s$. It is easy to see that the quantities $\hat{q}_{i}$ and $\hat{x}_{i, s}$ yield a feasible solution to ISOSP by satisfying $\sum_{s=1}^{S} \hat{q}_{i}+$ $\hat{x}_{i, s}=C_{s}$. Furthermore note that $\hat{x}_{j, s}=x_{j, s}^{*}-\sum_{s} \theta_{s} x_{j, s}^{*}$. Hence $\sum_{s} \theta_{s}\left(\hat{x}_{j, s}\right)^{2}<\sum_{s} \theta_{s}\left(x_{j, s}^{*}\right)^{2}$ since the expected value of $\hat{x}_{j, s}$ is zero.

Now, the objective function evaluated at $\hat{q}_{i}$ and $\hat{x}_{i, s}$ is given by

$$
\begin{aligned}
& \sum_{i} \sum_{s} \theta_{s}\left(a_{i} k_{i, s}+\sum_{i} \sum_{s} \theta_{s} \frac{d_{i}}{2}\left(\hat{x}_{i, s}\right)^{2}+\frac{b_{i}}{2}\left(k_{i, s}\right)^{2}\right) \\
& \quad+Y_{s} \sum_{i} k_{i, s}-\frac{Z}{2}\left(\sum_{i} k_{i, s}\right)^{2} .
\end{aligned}
$$

This value is strictly less than the objective evaluated at $q_{i}^{*}$ and $x_{i, s}^{*}$ (given by (13)), as we have already established that $\sum_{i} \sum_{s} \theta_{s}\left(d_{i} / 2\right)\left(x_{i, s}^{*}\right)^{2}>\sum_{i} \sum_{s} \theta_{s}\left(d_{i} / 2\right)\left(\hat{x}_{i, s}\right)^{2}$. This yields the contradiction that proves the result.
Corollary 1. In the stochastic problem ISOSP, if $q_{i}^{*}+$ $x_{i, s}^{*} \geqslant 0$ is satisfied $\forall s \in\{1, \ldots, S\}$ then $q_{i}^{*} \geqslant 0$ will hold.
Proof. In Lemma 1 we established that $\sum_{s} \theta_{s} x_{i, s}^{*}=0$. Therefore there exists a scenario $s^{\prime}$ such that $x_{i, s^{\prime}}^{*} \leqslant 0$. Clearly then $q_{i}^{*}+x_{i, s^{\prime}}^{*} \geqslant 0$ implies $q_{i}^{*} \geqslant 0$.

Discussion. Lemma 1 is the crucial result that drives the rest of our characterizations. This result hinges on the fact that we penalize quadratic deviation from the predispatch quantity. In the proof of Lemma 2, we demonstrate that the second stage of ISOSP reduces to selecting a contract point that minimizes the quadratic deviation penalty function that is known to be the mean of any distribution. For the quadratic penalty, this is irrespective of the distribution. (It is possible to also use an absolute value based deviation penalty and require a symmetric demand distribution. When the penalty function is an absolute value, the point of best estimate is the median of the distribution. For a symmetric distribution, of course this reduces again to the mean.) This model penalizes the deviations upward and downward identically. Therefore the predispatch point is optimized based on the mean demand scenario. The reader may argue that allowing for different upward and downward penalties is more realistic. However, as Pritchard et al. (2010) show, such
allowance of asymmetric penalties can lead to systematic arbitrage by the ISO, where a generator may be required to deviate upward "in every scenario" simply to increase expected welfare. This may be deemed undesirable for a market clearing mechanism. For this reason and to aid analytical computations, we have confined our attention to the symmetric upward and downward penalty case for this paper, which guarantees systematic arbitrage will not occur. We now use the above results to prove that the ISO's optimization problem can be viewed as a two-period settlement system where unlike NZTS, the deviation penalties are explicitly stated in the ISO's problem in the second period.

Lemma 2. The objective function of ISOSP is equivalent to the following function, which is separable in the predispatch and the spot market variables

$$
\begin{aligned}
z= & \sum_{i=1}^{n}\left(a_{i} q_{i}+\frac{b_{i}}{2} q_{i}^{2}\right)-Y \sum_{i=1}^{n} q_{i}+\frac{Z}{2}\left(\sum_{i=1}^{n} q_{i}\right)^{2} \\
& +\sum_{i=1}^{n}\left(\frac{b_{i}+d_{i}}{2} \sum_{s=1}^{S} \theta_{s} x_{i, s}^{2}\right)-\sum_{i=1}^{n} \sum_{s=1}^{S} \theta_{s} Y_{s} x_{i, s} \\
& +\frac{Z}{2} \sum_{s=1}^{S} \theta_{s}\left(\sum_{i=1}^{n} x_{i, s}\right)^{2} .
\end{aligned}
$$

Proof. Substituting for $C_{s}$ from constraints into the objective function of ISOSP yield

$$
\begin{aligned}
z= & \sum_{i=1}^{n}\left(a_{i} q_{i}+\frac{b_{i}}{2} q_{i}^{2}\right)-Y \sum_{i=1}^{n} q_{i}+\frac{Z}{2}\left(\sum_{i=1}^{n} q_{i}\right)^{2} \\
& +\sum_{i=1}^{n}\left(\frac{b_{i}+d_{i}}{2} \sum_{s=1}^{S} \theta_{s} x_{i, s}^{2}\right)-\sum_{i=1}^{n} \sum_{s=1}^{S} \theta_{s} Y_{s} x_{i, s} \\
& +\frac{Z}{2} \sum_{s=1}^{S} \theta_{s}\left(\sum_{i=1}^{n} x_{i, s}\right)^{2}+\sum_{i=1}^{n}\left(a_{i} \sum_{s=1}^{S} \theta_{s} x_{i, s}\right) \\
& +\sum_{i=1}^{n}\left(q_{i} b_{i} \sum_{s=1}^{S} \theta_{s} x_{i, s}\right)+\sum_{s=1}^{S} \theta_{s} Z \sum_{i=1}^{n} \sum_{j=1}^{n} q_{i} x_{j, s} .
\end{aligned}
$$

We have split the objective in three parts above. Note that the first part of the objective above is exclusively a function of predispatch quantities $q_{i}$ and the second only a function of the spot dispatches $x_{i, s}$. The third segment can be eliminated at optimality since in Lemma 1 we proved that $\sum_{s=1}^{S} \theta_{s} x_{j, s}=0$ for the optimal choice of real-time dispatches.

Note. We have therefore established that ISOSP reduces to a two-period single settlement model very similar to NZTS but with penalties $d_{i}$ explicitly present in the second period.

The rest of this section is devoted to deriving explicit expressions for the solution of ISOSP. In the next section we will use these expressions to arrive at best response functions for the firms and subsequently in
constructing an equilibrium for the stochastic market settlement. To simplify the equations and arrive at explicit solutions, we will transform the space of the parameters of ISOSP (i.e., the firm decision variables), much in the same way that we did in Section 3. If we now define $R_{i}=1 /\left(b_{i}+d_{i}\right)$ and $R=\sum_{i} R_{i}$, ISOSP reduces to minimizing the following:

$$
\begin{aligned}
& \sum_{i=1}^{n}\left(\frac{A_{i}}{B_{i}} q_{i}+\frac{1}{2 B_{i}} q_{i}^{2}\right)-Y \sum_{i=1}^{n} q_{i}+\frac{Z}{2}\left(\sum_{i=1}^{n} q_{i}\right)^{2} \\
& \quad+\sum_{s=1}^{S} \theta_{s}\left[\sum_{i=1}^{n} \frac{1}{2 R_{i}} x_{i, s}^{2}-\left(Y_{s}-Y\right) \sum_{i=1}^{n} x_{i, s}+\frac{Z}{2}\left(\sum_{i=1}^{n} x_{i, s}\right)^{2}\right]
\end{aligned}
$$

Note that as before (Lemma 2), the problem is separable in $q_{i}{ }^{\prime}$ s and $x_{i, s}$ 's, we can therefore solve the two stages separately. Note also that the problem in each stage is a convex optimization problem, therefore the first-order conditions will readily produce the optimal solution.

Proposition 5. If $(q, x, f, p)$ represents the solution of ISOSP, then we have

$$
\begin{gather*}
q_{i}=\frac{(Y+Z A) B_{i}}{1+Z B}-A_{i},  \tag{15}\\
x_{i, s}=\frac{\left(Y_{s}-Y\right) R_{i}}{1+Z R},  \tag{16}\\
f=\frac{Y+Z A}{1+Z B}, \quad p_{s}=\frac{Y+Z A}{1+Z B}+\frac{Y s-Y}{1+Z R} .
\end{gather*}
$$

Proof. For derivation of the expressions for the optimal solution above from first-order conditions please refer to the e-companion.

Observe from the expression for $f$ that this forward price (paid on predispatch quantities) is independent of any deviation costs in the spot market.
Corollary 2. In the solution of ISOSP, forward price is equal to the expected spot market price.
Proof. Since $Y=\Sigma_{s} \theta_{s} Y_{s}$, it is immediately obvious that $f=\sum_{s} \theta_{s} p_{s}$ as required.

### 4.3. Equilibrium Analysis of the Stochastic Settlement Market (ISOSP)

In Section 4.1 we presented firm $i$ 's profit under scenario $s$ in Equation (12). In our market model, we assume that all firms are risk neutral and therefore interested only in maximizing their expected profit. Firm $i$ 's expected profit (using the results of Corollary 2 ) is given by

$$
\begin{align*}
& u_{i}=f q_{i}+\sum_{s=1}^{s} \theta_{s}\left(p_{s} x_{i, s}-\left(\alpha\left(q_{i}+x_{i, s}\right)\right.\right. \\
&\left.\left.+\frac{\beta}{2}\left(q_{i}+x_{i, s}\right)^{2}+\frac{\delta}{2} x_{i, s}^{2}\right)\right) . \tag{17}
\end{align*}
$$

The above expression for $u_{i}$ can be expanded and we can observe that

$$
\begin{aligned}
u_{i}= & f q_{i}-\left(\alpha q_{i}+\frac{\beta}{2} q_{i}^{2}\right)+\sum_{s=1}^{S} \theta_{s}\left(p_{s} x_{i, s}-\frac{\beta+\delta}{2} x_{i, s}^{2}\right) \\
& -\alpha \sum_{s=1}^{S} \theta_{s} x_{i, s}-\beta q_{i} \sum_{s=1}^{S} \theta_{s} x_{i, s} .
\end{aligned}
$$

Note that from Lemma 1, the generator would know that for any admissible bid, the corresponding expected deviation from predispatch quantities $\sum_{s=1}^{S} \theta_{s} x_{i, s}=0$. Therefore the expected profit for the generator becomes

$$
u_{i}=f q_{i}-\left(\alpha q_{i}+\frac{\beta}{2} q_{i}^{2}\right)+\sum_{s=1}^{s} \theta_{s}\left(p_{s} x_{i, s}-\frac{\beta+\delta}{2} x_{i, s}^{2}\right) .
$$

We can use the expressions obtained from Proposition 5 to write $u_{i}$ as follows:

$$
\begin{align*}
u_{i}= & -\frac{1}{2} \beta A_{i}^{2}+\frac{A_{i}\left(-Z A+\alpha+Z B \alpha+Z A \beta B_{i}+Y\left(-1+\beta B_{i}\right)\right)}{1+Z B} \\
& +\frac{1}{2(1+Z B)^{2}(1+Z R)^{2}}\left(2(1+Z R)^{2}(Z A+Y)\right. \\
& \cdot(Z A+Y-(1+Z B) \alpha) B_{i}-(1+Z R)^{2}(Z A+Y)^{2} \beta B_{i}^{2} \\
& \left.+(1+Z B)^{2} R_{i}\left(-2+(\beta+\delta) R_{i}\right)\left(Y^{2}-\sum_{s} \theta_{s} Y_{s}^{2}\right)\right) . \tag{18}
\end{align*}
$$

Although this expression of the expected profit for the generator is rather ugly, it does have the advantage that upon differentiating with respect to $R_{i}$, all dependence on $A_{i}$ and $B_{i}$ drops and we are left with

$$
\begin{align*}
\frac{\partial u_{i}}{\partial R_{i}}=( & \left(Y^{2}-\sum_{s} \theta_{s} Y_{s}^{2}\right)\left(-1+(Z+\beta+\delta) R_{i}\right. \\
& \left.\left.+Z R_{-i}\left(-1+(\beta+\delta) R_{i}\right)\right)\right) \cdot \frac{1}{1+Z R^{3}} \tag{19}
\end{align*}
$$

where $R_{-i}=\sum_{j \neq i} R_{j}$. The fact that this derivative is free of $A_{i}$ and $B_{i}$ indicates that $u_{i}$ is separable in $R_{i}$ and $\left(A_{i}, B_{i}\right)$, that is

$$
\begin{equation*}
u_{i}\left(A_{i}, B_{i}, R_{i}\right)=g_{i}\left(A_{i}, B_{i}\right)+h_{i}\left(R_{i}\right) \tag{20}
\end{equation*}
$$

Because of this natural separability, our equilibrium analysis will focus on finding best responses in terms of $A_{i}, R_{i}$, and $B_{i}$, very similar to the NZTS section.

Equation (20) enables us to maximize $u_{i}$ by maximizing $g_{i}$ and $h_{i}$ over $\left(A_{i}, B_{i}\right)$ and $R_{i}$, respectively. This is helpful as we can establish quasiconcavity results for $g_{i}$ and $h_{i}$ separately.

We start our investigations by examining $g_{i}$. The full expression for $g_{i}$ can be found in the e-companion. Holding $B_{i}$ fixed, note that

$$
\frac{\partial^{2} g_{i}}{\partial A_{i}^{2}}=-\frac{\left(1+Z B_{-i}\right)\left(2 Z+\beta+Z \beta B_{-i}\right)}{(1+Z B)^{2}}
$$

Figure 1. (Color online) Two Views of the Graph of Function $g_{i}$


Note. Note that the optimal value of $g_{i}$ is obtained along a continuum, for any value of $B_{i}$.

This demonstrates that $g_{i}$ is concave in $A_{i}$ for any fixed $B_{i}$. Furthermore, for any fixed $B_{i}$, we can use the first-order conditions to find $A_{i}^{*}\left(B_{i}\right)$, i.e., the value of $A_{i}$ that maximizes $g_{i}\left(A_{i}, B_{i}\right)$ for the fixed $B_{i}$ :

$$
\begin{align*}
A_{i}^{*}\left(B_{i}\right)= & {\left[\left(1+Z B_{-i}\right)\left(\alpha-Z A_{-i}+Z \alpha B-Y\right)\right.} \\
& \left.+\left(Y+Z A_{-i}\right)\left(Z+\beta+Z \beta B_{-i}\right) B_{i}\right] \\
& \cdot\left[\left(1+Z B_{-i}\right)\left(2 Z+\beta+Z \beta B_{-i}\right)\right]^{-1} . \tag{21}
\end{align*}
$$

To find the optimal value for $g_{i}$, we substitute the expression for $A_{i}^{*}\left(B_{i}\right)$ in $g_{i}\left(A_{i}^{*}\left(B_{i}\right), B_{i}\right)$. Surprisingly, upon undertaking this substitution, it can be observed that $g_{i}\left(A_{i}^{*}\left(B_{i}\right), B_{i}\right)$ is a constant. Figure 1 depicts $g_{i}$.

To uncover the intuition behind this feature of $g_{i}$, we can offer the following mathematical explanation. We observe that

$$
\begin{aligned}
\frac{\partial g_{i}}{\partial A_{i}}=[ & -\left(1+Z B_{-i}\right)\left(Y-\alpha+Z A_{-i}+(2 Z+\beta) A_{i}\right. \\
& \left.\left.+Z B_{-i}\left(-\alpha+\beta A_{i}\right)\right)\right] \cdot\left[(1+Z B)^{2}\right]^{-1} \\
+ & {\left[\left(Z(Y+\alpha)+Y \beta+Y(Z \alpha+Y \beta) B_{-i}\right.\right.} \\
& \left.\left.+Z A_{-i}\left(Z+\beta+Z \beta B_{-i}\right)\right) B_{i}\right] \cdot\left[(1+Z B)^{2}\right]^{-1},
\end{aligned}
$$

and that

$$
\frac{\partial g_{i}}{\partial B_{i}}=-\frac{Y+Z A}{1+Z B} \cdot \frac{\partial g_{i}}{\partial A_{i}} .
$$

Therefore, stationary conditions enforced in $A_{i}$ will also imply stationarity in $B_{i}$.
As $g_{i}\left(A_{i}^{*}\left(B_{i}\right), B_{i}\right)$ is constant for any $B_{i}>0$, for any value of $B_{i}>0$, the tuple $\left(A_{i}^{*}\left(B_{i}\right), B_{i}\right)$ is an argmax of $g_{i}$ for any positive $B_{i}$. Let $D_{i}$ denote $1 /\left(d_{i}+\varepsilon\right)$. Recall that according to our initial assumptions, we have $b_{i} \geqslant \varepsilon$, thus $R_{i} \leqslant D_{i}$.
The following analysis on $h_{i}$ will explain how opti$\mathrm{mal} R_{i}$ is constrained by the value of $D_{i}$.
Proposition 6. Suppose that $R_{-i}$ is fixed. Then $h_{i}$ is optimized at

$$
R_{i}^{*}=\min \left\{D_{i}, \frac{1+Z R_{-i}}{Z+\beta+\delta+Z(\beta+\delta) R_{-i}}\right\}
$$

Proof. Note that at

$$
\begin{equation*}
\hat{R}_{i}=\frac{1+Z R_{-i}}{Z+\beta+\delta+Z(\beta+\delta) R_{-i}} \tag{22}
\end{equation*}
$$

the derivative $\partial h_{i} / \partial R_{i}=\partial u_{i} / \partial R_{i}$ vanishes. Also recall from Jensen's inequality that $Y^{2} \leqslant \Sigma_{s} \theta_{s} Y_{s}^{2}$. It can therefore be seen from (19) that this derivative is positive for $R_{i}<\hat{R}_{i}$ and negative for $R_{i}>\hat{R}_{i}$.

Recall further that the definitions of $D_{i}$ and $R_{i}$ require $R_{i} \leqslant D_{i}$. Therefore, in optimizing $h_{i}$, we need to enforce this constraint and we obtain

$$
R_{i}^{*}=\min \left\{D_{i}, \frac{1+Z R_{-i}}{Z+\beta+\delta+Z(\beta+\delta) R_{-i}}\right\} .
$$

We now return to $u_{i}$, the expected profit function for firm $i$. As $u_{i}\left(A_{i}, B_{i}, R_{i}\right)=g_{i}\left(A_{i}, B_{i}\right)+h_{i}\left(R_{i}\right)$, we can start by obtaining the maximum value of $g_{i}$ attained at a point $\left(A_{i}^{*}\left(B_{i}\right), B_{i}\right)$ for any positive $B_{i}$. Subsequently, we proceed to optimize $h_{i}\left(R_{i}\right)$. Proposition (6) readily delivers the optimal $R_{i}$. We have therefore proved the following theorem.

Theorem 1. The best response of firm $i$, holding competitor offers fixed, is to offer any $d_{i}$ for which we have

$$
\frac{1}{d_{i}+\varepsilon} \geqslant \frac{1+Z R_{-i}}{Z+\beta+\delta+Z(\beta+\delta) R_{-i}} .
$$

For any such $d_{i}$, optimal $a_{i}$ and $b_{i}$ can be computed from the following equations:

$$
\begin{aligned}
R_{i}= & \frac{1+Z R_{-i}}{Z+\beta+\delta+Z(\beta+\delta) R_{-i}}, \\
A_{i}= & {\left[\left(1+Z B_{-i}\right)\left(\alpha-Z A_{-i}+Z \alpha B-Y\right)+\left(Y+Z A_{-i}\right)\right.} \\
& \left.\cdot\left(Z+\beta+Z \beta B_{-i}\right) B_{i}\right] \cdot\left[\left(1+Z B_{-i}\right)\left(2 Z+\beta+Z \beta B_{-i}\right)\right]^{-1} .
\end{aligned}
$$

Theorem 1 indicates that the game has multiple (infinite) symmetric equilibria.

### 4.4. Equilibrium Analysis of the Stochastic Settlement Market with Fixed Deviation Costs (ISOSP-FD)

Following Theorem 1, we are presented with an opportunity to assess a market clearing mechanism where the strategy space of the agents is reduced in dimension. Instead of bidding in parameters $\left(a_{i}, b_{i}, d_{i}\right)$, in this variation the firms offer a supply function parametrised by $\left(a_{i}, b_{i}\right)$ and the deviation penalty is fixed (and reflected in market clearing), by the ISO. We call this variation ISOSP-FD with $d_{i}=d^{\text {SO }}$ and known to the firms prior to the start of bidding. We show that for a range of $d^{\text {SO }}$ starting anywhere above zero, building up to the true deviation cost and even beyond, the total welfare increases, in comparison to the NZTS model. This in turn demonstrates that having a deviation cost parameter, even though it may not be quite accurate, can enhance efficiency.

Proposition 7. The unique symmetric equilibrium quantities of ISOSP-FD are as follows:

$$
\begin{align*}
b_{i}= & \max \left\{\varepsilon,\left(-Z(n-2)+\beta+\delta+\sqrt{Z}^{2}(n-2)^{2}\right.\right. \\
& \left.\left.+2 Z n(\beta+\delta)+(\beta+\delta)^{2}\right) \cdot \frac{1}{2}-d^{\text {SO }}\right\}  \tag{23}\\
a_{i}= & {\left[\alpha-Y+B_{i}(-Z(Y(n-2)-(2 n-1) \alpha)+Y \beta\right.} \\
& \left.\left.+Z(n-1)(Z n \alpha+Y \beta) B_{i}\right)\right] \\
& \cdot\left[B_{i}\left(Z(n+1)+\beta+Y(n-1)(Z n+\beta) B_{i}\right)\right]^{-1} . \tag{24}
\end{align*}
$$

The proof of the above proposition is contained in the e-companion.
Let us define

$$
\hat{d}=\frac{-Z(n-2)+\beta+\delta+\sqrt{Z^{2}(n-2)^{2}+2 Z n(\beta+\delta)+(\beta+\delta)^{2}}}{2} .
$$

Theorem 2. For ISOSP-FD with $d^{\text {SO }} \leqslant \hat{d}-\varepsilon$, as the number of participating firms increases, they tend to offer their true cost parameters. In other words,

$$
\begin{gathered}
\lim _{n \rightarrow \infty} a_{i}=\alpha \\
\lim _{n \rightarrow \infty} b_{i}+d^{\text {SO }}=\beta+\delta
\end{gathered}
$$

When the fixed parameter $d^{\text {SO }}$ is chosen to be equal to $\delta$, $\lim _{n \rightarrow \infty} b_{i}=\beta$.
Proof. The equations are simply derived from the equilibrium values of $a_{i}$ and $d_{i}$ given in Proposition 7.

Theorem 2 shows that the ISOSP-FD market is behaving competitively in the sense that when number of firms increases, they offer their true cost parameters.

One important feature of the equilibrium values are the nonnegativity of the predispatch and dispatch. This is important, because we neglected the nonnegativity constraints in ISOSP in the first place.

Proposition 8. Let $\left(\mathbf{q}^{*}, \mathbf{x}^{*}\right)$ represent an equilibrium of ISOSP-FD. Then the following inequalities hold:

$$
\begin{gathered}
\forall i, s: \quad q_{i}^{*}+x_{i, s}^{*} \geqslant 0 \\
\forall i: \quad q_{i}^{*} \geqslant 0 .
\end{gathered}
$$

The proof of the above proposition is contained in the e-companion.

Though, the equilibrium predispatch and dispatch are nonnegative, one might raise an objection that a game without the nonnegativity constraints embedded in the ISO's optimization problem, is different from the original game. Therefore, there is no assurance the found equilibrium is also the equilibrium of the original game. The following theorem states that the obtained equilibrium values are also the equilibrium of the original game with nonnegativity constraints. The proof of this theorem is quite lengthy and consists of several technical lemmas.

Theorem 3. The equilibrium of the symmetric stochastic settlement game without the nonnegativity constraints in ISOSP-FD is also the equilibrium of the stochastic settlement game with the nonnegativity constraints.
Proof. Please refer to the e-companion for the proof of this theorem.

## 5. Comparison of the Two Markets

We are interested in the performance of the two market clearing mechanisms ISOSP-FD and NZTS, under strategic behaviour. Our criterion for comparing the two models is social welfare. Social welfare is defined as the sum of the consumer and producer welfare and in our market environments this reduces to

$$
\begin{align*}
\mathrm{W}= & \sum_{s=1}^{S} \theta_{s}\left(Y_{s}\left(\sum_{i=1}^{n} y_{i, s}\right)-\frac{Z}{2}\left(\sum_{i=1}^{n} y_{i, s}\right)^{2}\right) \\
& -\sum_{s=1}^{S} \theta_{s}\left(\sum_{i=1}^{n}\left(\alpha y_{i, s}+\frac{\beta}{2} y_{i, s}{ }^{2}+\frac{\delta}{2}\left(y_{i, s}-q_{i}\right)^{2}\right)\right) . \tag{25}
\end{align*}
$$

Note that the different social welfare values $\mathrm{W}^{\mathrm{SS}}$ (for the ISOSP-FD) and $\mathrm{W}^{\text {NZTS }}$ (for the NZTS mechanism) are found through the same formula, however with the different equilibrium $y_{i, s}$ variables.

Recall that following Theorem 1 the choice of $d^{\text {SO }}$ was delegated to the ISO. The next theorem establishes that when firms are bidding strategically, the stochastic settlement market dominates the NZTS market for any choice of $d^{\mathrm{SO}} \in(0, \hat{d})$.

Theorem 4. The social welfare of ISOSP-FD is an increasing function of the parameter $d^{\text {SO }}$, and it is higher than the NZTS social welfare, provided $d^{\text {SO }}$ is chosen less than or equal to the threshold value $\hat{d}-\varepsilon$.

Proof. To prove the proposition, we show when $d^{\mathrm{SO}}=0$, then $\mathrm{W}^{\mathrm{SS}}=\mathrm{W}^{\text {NZTS }}$. We then demonstrate $\mathrm{W}^{\mathrm{SS}}$ is an increasing function of $d^{\mathrm{SO}}$ for $0 \leqslant d^{\mathrm{SO}} \leqslant \hat{d}-\varepsilon$, and therefore, $\mathrm{W}^{\mathrm{SS}} \geqslant \mathrm{W}^{\mathrm{NZTS}}$, when $d^{\mathrm{SO}} \leqslant \hat{d}-\varepsilon$ (note that $\mathrm{W}^{\text {NZTS }}$ is a constant and does not change with $d^{\text {SO }}$ ).

When $d^{\text {SO }}=0$, Equations (24), (9), and (8) yield that the equilibrium quantities are identical in the stochastic settlement and two-period settlement markets. That is,

$$
B_{i}^{\mathrm{SS}}=B_{i}^{\mathrm{NZTS}}, A_{i}^{\mathrm{SS}}=A_{i}^{\mathrm{NZTS}}, \quad R_{i}^{\mathrm{SS}}=B_{i}^{\mathrm{SS}} .
$$

Here we can simplify the expressions for $y_{i, s}$ and $q_{i}$ (from Propositions 1, 2, and 5) to obtain

$$
\begin{aligned}
q_{i}^{\mathrm{SS}} & =q_{i}^{\mathrm{NZTS}}=\frac{Y B_{i}-A_{i}}{1+\mathrm{ZB}}, \\
y_{i, s}^{\mathrm{SS}} & =y_{i, \mathrm{~s}}^{\mathrm{NZTS}}=\frac{Y_{s} B_{i}-A_{i}}{1+Z B} .
\end{aligned}
$$

Therefore social welfare of these models (Equation (25)) are the same provided $d^{\mathrm{SO}}=0$. We can rewrite the social welfare expression (25) as

$$
\begin{align*}
\mathrm{W}=\sum_{s=1}^{s} & \theta_{s}\left(Y_{s}\left(\sum_{i=1}^{n} y_{i, s}\right)-\frac{Z}{2}\left(\sum_{i=1}^{n} y_{i, s}\right)^{2}\right. \\
& \left.-\sum_{i=1}^{n}\left(\alpha y_{i, s}+\frac{\beta}{2} y_{i, s}{ }^{2}+\frac{\delta}{2} x_{i, s}{ }^{2}\right)\right) . \tag{26}
\end{align*}
$$

Note that the expression for social welfare is the same for both models and only depends on the corresponding quantities dispatched from each model (i.e., $y_{i, s}^{\mathrm{SS}}$ versus $y_{i, s}^{\mathrm{NZTS}}$, etc.).

Note that, according to the results of Proposition 7, for $0 \leqslant d^{\mathrm{SO}} \leqslant \hat{d}-\varepsilon$, we have $b_{i}=\hat{d}-d^{\mathrm{SO}}$, and therefore $R_{i}$ has a constant value of $1 / \hat{d}$, while $B_{i}$ is a function of $d^{\text {SO }}$. Furthermore, note that $x_{i, s}^{\mathrm{SS}}$ is independent of $d^{\mathrm{SO}}$, and therefore

$$
\begin{equation*}
\frac{\partial \mathrm{W}^{\mathrm{SS}}}{\partial d^{\mathrm{SO}}}=\frac{1}{\left(\hat{d}-d^{\mathrm{SO}}\right)^{2}} \sum_{i, s} \frac{\partial \mathrm{~W}^{\mathrm{SS}}}{\partial y_{i, s}^{\mathrm{SS}}} \frac{\partial y_{i, s}^{\mathrm{SS}}}{\partial B_{i}} \tag{27}
\end{equation*}
$$

On the other hand, taking the derivative of $y_{i, s}^{\mathrm{SS}}$ with respect to $B_{i}$ we obtain

$$
\frac{\partial y_{i, s}^{\mathrm{SS}}}{\partial B_{i}}=\frac{(Y-\alpha)(n-1) Z^{2}}{\left(Z+n Z+\beta+(n-1) Z(n Z+\beta) B_{i}\right)^{2}} \geqslant 0
$$

The right-hand side is readily seen to be nonnegative as $Y>\alpha$ and $n>1$.

As $\partial y_{i, s}^{\mathrm{SS}} \partial B_{i}$ is independent of firm $i$ and scenario $s$ (note that $\left.B_{i}=\left(\hat{d}-d^{\mathrm{SO}}\right)^{-1}\right)$, we can rearrange (27) and obtain

$$
\frac{\partial \mathrm{W}^{\mathrm{SS}}}{\partial d^{\mathrm{SO}}}=\frac{1}{\left(\hat{d}-d^{\mathrm{SO}}\right)^{2}} \frac{\partial y_{i, s}^{\mathrm{SS}}}{\partial B_{i}} \sum_{i, s} \frac{\partial \mathrm{~W}^{\mathrm{SS}}}{\partial y_{i, s}^{\mathrm{SS}}}
$$

On the other hand, differentiating (26) yields

$$
\frac{\partial \mathrm{W}^{\mathrm{SS}}}{\partial y_{i, s}^{\mathrm{SS}}}=\theta_{s}\left(Y_{s}-\alpha-(\mathrm{Zn}+\beta) y_{i, s}^{\mathrm{SS}}\right)
$$

Hence

$$
\begin{aligned}
\sum_{s} \frac{d \mathrm{~W}^{\mathrm{SS}}}{d y_{i, s}^{\mathrm{SS}}} & =Y-\alpha-(\mathrm{Z} n+\beta) q_{i}^{\mathrm{SS}} \\
& =\frac{b \mathrm{Z}(Y-\alpha)}{\mathrm{Z}(n-1)(n \mathrm{Z}+\beta)+b((n+1) \mathrm{Z}+\beta)} \geqslant 0
\end{aligned}
$$

Therefore we can conclude that

$$
\frac{\partial \mathrm{W}^{\mathrm{SS}}}{\partial d^{\mathrm{SO}}} \geqslant 0
$$

Note that we can easily show that

$$
\hat{d} \geqslant \beta+\delta
$$

and therefore, if the fixed $d_{i}$ is chosen equal to $\delta$ then $\mathrm{W}^{\mathrm{SS}} \geqslant \mathrm{W}^{\text {NZTS }}$.

Proposition 9. The social welfare of ISOSP-FD is maximized if the parameter $d^{\mathrm{SO}}$ is chosen equal to the threshold value $\hat{d}-\varepsilon$.
Proof. We have established (Theorem 4) that $\partial \mathrm{W}^{\mathrm{SS}} /$ $\partial d^{\mathrm{SO}} \geqslant 0$, for $0 \leqslant d^{\mathrm{SO}} \leqslant \hat{d}-\varepsilon$. To prove this proposition, we demonstrate that for $d^{\text {SO }}>\hat{d}-\varepsilon$, we have $\partial \mathrm{W}^{\mathrm{SS}} / \partial d^{\mathrm{SO}} \leqslant 0$. Under this condition, according to the equilibrium formulae, we have $b_{i}=\varepsilon$, and therefore, changing $d^{\text {SO }}$ only modifies the equilibrium value of $R_{i}$ (and not $A_{i}$ and $B_{i}$ ). Therefore, we have
$\frac{\partial \mathrm{W}^{\mathrm{SS}}}{\partial d^{\mathrm{SO}}}=-\frac{1}{\left(\varepsilon+d^{\mathrm{SO}}\right)^{2}} \sum_{i, s}\left[\frac{\partial \mathrm{~W}^{\mathrm{SS}}}{\partial y_{i, s}^{\mathrm{SS}}} \frac{\partial y_{i, s}^{\mathrm{SS}}}{\partial R_{i}}+\frac{\partial \mathrm{W}^{\mathrm{SS}}}{\partial x_{i, s}^{\mathrm{SS}}} \frac{\partial x_{i, s}^{\mathrm{SS}}}{\partial R_{i}}\right]$.
Note that $q_{i}$ is independent of $R_{i}$, and hence

$$
\frac{\partial y_{i, s}^{\mathrm{SS}}}{\partial R_{i}}=\frac{\partial x_{i, s}^{\mathrm{SS}}}{\partial R_{i}}=\frac{Y_{s}-Y}{\left(1+n \mathrm{Z} R_{i}\right)^{2}}
$$

On the other hand, differentiating (26) yields

$$
\begin{gathered}
\frac{\partial \mathrm{W}^{\mathrm{SS}}}{\partial y_{i, s}^{\mathrm{SS}}}=\theta_{s}\left(Y_{s}-\alpha-(\mathrm{Zn}+\beta) y_{i, s}^{\mathrm{SS}}\right) \\
\frac{\partial \mathrm{W}^{\mathrm{SS}}}{\partial x_{i, s}^{\mathrm{SS}}}=\theta_{s}\left(-\delta x_{i, s}^{\mathrm{SS}}\right)
\end{gathered}
$$

Therefore, we conclude

$$
\begin{aligned}
\frac{\partial \mathrm{W}^{\mathrm{SS}}}{\partial d^{\mathrm{SO}}}= & -\frac{1}{\left(\varepsilon+d^{\mathrm{SO}}\right)^{2}} \sum_{i, s} \frac{\partial \mathrm{~W}^{\mathrm{SS}}}{\partial y^{\mathrm{SS}}{ }_{i, s}} \frac{\partial y_{i, s}^{\mathrm{SS}}}{\partial R_{i}}+\frac{\partial \mathrm{W}^{\mathrm{SS}}}{\partial x_{i, s}^{\mathrm{SS}}} \frac{\partial x_{i, s}^{\mathrm{SS}}}{\partial R_{i}} \\
= & -\frac{1}{\left(\varepsilon+d^{\mathrm{SO}}\right)^{2}} \sum_{i, s} \frac{\theta_{s}\left(Y_{s}-Y\right)}{\left(1+n \mathrm{ZR} R_{i}\right)^{2}} \\
& \cdot\left(Y_{s}-\alpha-(\mathrm{Z} n+\beta) y_{i, s}^{\mathrm{SS}}-\delta x_{i, s}^{\mathrm{SS}}\right) \\
= & -\frac{1}{\left(\varepsilon+d^{\mathrm{SO}}\right)^{2}\left(1+n \mathrm{ZR} R_{i}\right)^{2}} \sum_{i, s} \theta_{s}\left(Y_{s}-Y\right) \\
& \cdot\left(Y_{s}-\alpha-(\mathrm{Zn}+\beta) y_{i, s}^{\mathrm{SS}}-\delta x_{i, s}^{\mathrm{SS}}\right) .
\end{aligned}
$$

To prove the theorem, we show $K_{i}=\sum_{s} \theta_{s}\left(Y_{s}-Y\right)$. $\left(Y_{s}-\alpha-(\mathrm{Z} n+\beta) y_{i, s}^{\mathrm{SS}}-\delta x_{i, s}^{\mathrm{SS}}\right) \geqslant 0$ for any $i$. Note that $y_{i, s}^{\mathrm{SS}}=q_{i}^{\mathrm{SS}}+x_{i, s}^{\mathrm{SS}}$, and thus

$$
\begin{aligned}
K_{i}= & \sum_{s} \theta_{s}\left(Y_{s}-Y\right)\left(Y_{s}-\alpha-(\mathrm{Z} n+\beta) y_{i, s}^{\mathrm{SS}}-\delta x_{i, s}^{\mathrm{SS}}\right) \\
= & \sum_{s} \theta_{s} Y_{s}^{2}-Y^{2}-\left(\alpha+\mathrm{Zn} q_{i}^{\mathrm{SS}}+\beta q_{i}^{\mathrm{SS}}\right) \sum_{s} \theta_{s}\left(Y_{s}-Y\right) \\
& -(\mathrm{Z} n+\beta+\delta) \sum_{s} \theta_{s}\left(Y_{s}-Y\right) x_{i, s}^{\mathrm{SS}} .
\end{aligned}
$$

Replacing $\sum_{s} \theta_{s}\left(Y_{s}-Y\right)$ with zero and inputting the value of $x_{i, s}^{\mathrm{SS}}=\left(\left(Y_{s}-Y\right) R_{i}\right) /\left(1+n \mathrm{Z} R_{i}\right)$, we obtain

$$
\begin{aligned}
K_{i} & =\sum_{s} \theta_{s} Y_{s}^{2}-Y^{2}-(Z n+\beta+\delta) \sum_{s} \theta_{s}\left(Y_{s}-Y\right) \frac{\left(Y_{s}-Y\right) R_{i}}{1+n Z R_{i}} \\
& =\left(\sum_{s} \theta_{s} Y_{s}^{2}-Y^{2}\right)\left(1-\frac{(Z n+\beta+\delta) R_{i}}{1+n Z R_{i}}\right) \\
& =\left(\sum_{s} \theta_{s} Y_{s}^{2}-Y^{2}\right)\left(\frac{1-(\beta+\delta) R_{i}}{1+n Z R_{i}}\right) .
\end{aligned}
$$

As discussed earlier, $\beta+\delta<\hat{d}$, and thus $0<\beta+\delta<$ $\hat{d} \leqslant d^{\mathrm{SO}}<d^{\mathrm{SO}}+\varepsilon$. If we multiply this by the positive quantity $R_{i}=1 /\left(d^{\mathrm{SO}}+\varepsilon\right)$, we obtain $(\beta+\delta) R_{i}<1$. Thus, we have

$$
\frac{1-(\beta+\delta) R_{i}}{1+n Z R_{i}}>0
$$

Also, according to Jensen's inequality (or based on the nonnegativity property of variance), we can conclude $\operatorname{var}\left(Y_{s}\right)=\sum_{s} \theta_{s} Y_{s}^{2}-Y^{2} \geqslant 0$. These inequalities indicate that $K_{i} \geqslant 0$, and therefore, we can conclude

$$
\frac{\partial \mathrm{W}^{\mathrm{SS}}}{\partial d^{\mathrm{SO}}}=-\frac{1}{\left(\varepsilon+d_{i}\right)^{2}\left(1+n \mathrm{ZR} R_{i}\right)^{2}} \sum_{i} K_{i} \leqslant 0 .
$$

Example 1. Consider a market with two symmetric generators as defined in Table 1.

Figure 2 shows how the social welfare of the stochastic settlement mechanism is affected by the choice of $d^{\text {SO }}$. It also demonstrates that for $d^{\mathrm{SO}}<\hat{d}$ and even beyond, the stochastic settlement mechanism has a higher equilibrium social welfare in comparison with the NZTS mechanism. Note that at $d^{\text {SO }}=\hat{d}$, the equilibrium $b_{i}$ is set to $\varepsilon$ and social welfare is maximized. For the rest of this example, we assume that the ISO chooses $d^{\text {SO }}=0.5$, which ensures higher equilibrium

Table 1. The Market Environment for the Example

| Parameter | Value |
| :--- | :---: |
| $\alpha, \beta, \delta$ | $50,1,0.5$ |
| $Y_{1}, Y_{2}, Z$ | $100,150,1$ |
| $\theta_{1}, \theta_{2}$ | $0.5,0.5$ |
| $n$ | 2 |

Figure 2. (Color online) The Effect of $d^{\text {SO }}$ on the Social Welfare of the Stochastic Settlement Model and on How It Compares to the Two Period Settlement Mechanism


Note. The thicker line traces ISOSP-FD welfare whereas the thinner line traces the NZTS welfare.
social welfare from the stochastic settlement in comparison with the NZTS mechanism.

Another interesting experiment is to investigate the effect of $\beta$ and $\delta$ on these mechanisms.

Figures 3-5 compare the ISOSP-FD and the NZTS mechanisms for this example, however for different $\beta$ and $\delta$ values. A first observation is that the stochastic settlement mechanism increases social and consumer welfare and decreases producer welfare in comparison with the two settlement mechanism.

It is also interesting to investigate the effect of competition on these mechanisms. To do so, we can test the effect of number of firms on these mechanism.

Figure 6 shows the difference in the social welfare of our two mechanisms as a function of $n$. It shows that when the number of generators increases, the performance of the stochastic and two-period settlement mechanisms converge.

## 6. Robustness to Modelling Assumptions

In this section, we investigate the robustness of our results to two important model assumptions.

### 6.1. The Case of Asymmetric Generators

Thus far, we have derived the analytical expressions for a symmetric equilibrium. We have also proved that the stochastic settlement market always improves social welfare under this symmetric equilibrium. We now consider a duopoly with two asymmetric generators. As outlined in the introduction of this paper, there are a number of papers that are relevant to the work presented in this paper. However, none of the existing papers deals with the short-term penalty costs in a two-period market clearing paradigm. Furthermore, the simplification techniques that we have employed to derive analytical expressions for our symmetric case no

Figure 3. (Color online) Social Welfare of ISOSP-FD and NZTS for Different $\beta$ and $\delta$ Values


Note. The thicker lines trace ISOSP-FD welfare while the thin lines trace the NZTS welfare.
Figure 4. (Color online) Producer Welfare of ISOSP-FD and NZTS for Different $\beta$ and $\delta$ Values


Note. The thick lines trace ISOSP-FD producer welfare while the thin lines trace NZTS producer welfare.

Figure 5. (Color online) Consumer Welfare of ISOSP-FD and NZTS for Different $\beta$ and $\delta$ Values


Note. The thick lines trace ISOSP-FD consumer welfare while the thin lines trace NZTS consumer welfare.
longer apply here because of assumption of asymmetry. At this point, we use a computational method laid out in Section 6.1.3 to construct an equilibrium of our asymmetric game. In what follows, we will remind the reader of market assumptions, then restate the ISO's market clearing problem before proceeding to equilibrium computations.
6.1.1. The Market Environment in the Asymmetric Case. This environment is very similar to the setup for
the symmetric case. It has the following distinguishing features.

- The generators are no longer symmetric. To make the examples computationally tractable, we focus on two generator examples.
- We use the same form of long-run and short-run cost functions as the symmetric case. Here however, the firms are no longer identical and the cost parameters $\alpha_{i}, \beta_{i}$, and $\delta_{i}$ depend on the firm $i$.

Figure 6. (Color online) Social Welfare of the Two-Period Settlement Mechanism Converges to That of the Stochastic Mechanism When $n$ Increases


Notes. Competition increases with a bigger market. The thick line traces ISOSP-FD welfare while the thin line traces NZTS welfare.
6.1.2. Models. The ISO's optimization problem is similar to the symmetric case, however Theorem 8 no longer applies in the asymmetric case. Therefore to ensure the nonnegativity of the equilibrium, both for the twoperiod settlement and the stochastic programming market clearing mechanisms, we need to enforce nonnegativity in the ISO's problem. Thus, the predispatch problem of the ISO in the (asymmetric) NZTS mechanism is
PDATS: $\min _{q, Q} z, \quad z=\sum_{i=1}^{n}\left(a_{i} q_{i}+\frac{b_{i}}{2} q_{i}^{2}\right)-\left(Y Q-\frac{Z}{2} Q^{2}\right)$

$$
\begin{array}{ll}
\text { s.t. } & \sum_{i} q_{i}-Q=0, \quad[f] \\
& q_{i} \geqslant 0, \quad \forall i . \tag{29}
\end{array}
$$

The ISO's spot market optimization problem for scenario $s$ is
SATS(s): $\quad \min _{y_{s}, C_{s}} z, \quad z=\sum_{i=1}^{n}\left(a_{i} y_{i, s}+\frac{b_{i}}{2} y_{i, s}^{2}\right)-\left(Y_{s} C_{s}-\frac{Z}{2} C_{s}^{2}\right)$

$$
\begin{array}{ll}
\text { s.t. } & \sum_{i} y_{i, s}-C_{s}=0, \quad\left[p_{s}\right] \\
& y_{i, s} \geqslant 0, \quad \forall i . \tag{30}
\end{array}
$$

Similarly, the stochastic optimization problem of the ISO in the stochastic settlement mechanism can be represented as
SATS: min $z, z=\sum_{s=1}^{S} \theta_{s}\left(\sum_{i=1}^{n}\left[a_{i}\left(q_{i}+x_{i, s}\right)+\frac{b_{i}}{2}\left(q_{i}+x_{i, s}\right)^{2}\right.\right.$

$$
\left.\left.+\frac{d_{i}}{2} x_{i, s}^{2}\right]-\left(Y_{s} C_{s}-\frac{Z}{2} C_{s}^{2}\right)\right)
$$

$$
\text { s.t. } \sum_{i} q_{i}-Q=0, \quad[f]
$$

$$
Q+\sum_{i} x_{i, s}-C_{s}=0, \quad \forall s, \quad\left[p_{s}\right]
$$

$$
q_{i}+x_{i, s} \geqslant 0, \quad \forall i, s
$$

6.1.3. Equilibrium Computations. To find a Nash equilibrium to our games, we use a dynamic process. The
idea is to allow each participant in turn to update its strategies, assuming the strategy set of the other participants is fixed. If this diagonalization process terminates with no participant willing to deviate from its last strategy, then we have arrived at a Nash equilibrium. Note that by embedding the optimality conditions of the market clearing problems (for the NZTS, or the stochastic programming market clearing), the generator optimization problem becomes nonconvex and requires solving to global optimality. To do this, we have used the global solver of LINGO. The global solver of LINGO guarantees the optimality of its final solution using a branch-and-bound approach. Here a sequence of piecewise convex relaxations of the original (nonconvex) problem are solved. The convex relaxations are derived using bounds on the variables. If the optimal solution of the relaxed problem is feasible for the original problem, it is also the optimal point of the original problem. If not, further enhancement is made through dividing up the domain of the objective function and creating more accurate, piecewise convex functions on each part of the domain. The process of branching continues until all branches end with an optimal point. Note that user defined tolerances on the splitting procedure make this method a finite process. For more information about the mathematics behind this global solver, see Lin and Schrage (2009). The tolerance that we have used, as the minimum acceptable difference between best response strategies of firms in different turns, is of order of $10^{-10}$.
6.1.4. Sensitivity to Different Cost Structures (i.e., Generation Technologies). Different generation technologies have different structure in their cost functions, e.g., a particular generation technology may have a high generation cost but a low cost for fast deviation and another generator might be the opposite. In this section, we analyze a market with two asymmetric generators with various cost patterns (different layouts of $\alpha_{i}, \beta_{i}$, and, $\delta_{i}$ ). Without loss of generality we call the generator with the lower $\alpha_{i}$ value generator 1 and the other generator 2 . We then design different experiments with different possibilities for $\beta_{i}$ and $\delta_{i}$ (e.g., $\beta_{1}>\beta_{2}, \beta_{1}<\beta_{2}$, etc.). For each of these layouts, we consider two cases for $d^{\mathrm{SO}}: d^{\mathrm{SO}}=\min _{i}\left\{\delta_{i}\right\}$ and $d^{\mathrm{SO}}=$ $\max _{i}\left\{\delta_{i}\right\}$. Consider a market with two demand scenarios with parameters given in Table 2. Table 3 summarizes the difference between the equilibrium values of the SFSP-FD and NZTS mechanisms for each of these experiments. According to these results, SFSP-FD results in lower prices, profit, and producer welfare,

Table 2. Scenarios and Demand

| Scenarios | $\theta$ | $Y$ |
| :--- | :---: | :---: |
| 1 | 0.5 | 100 |
| 2 | 0.5 | 150 |

Table 3. Difference in the Equilibrium Values of the SFSP-FD and NZTS (i.e., SFSP-FD - NZTS) Under Asymmetry Assumption and Different Cost Patterns

| Ex. | Gen | $d^{\text {So }}$ | $f$ | $p\left(s_{1}\right)$ | $p\left(s_{2}\right)$ | Profit | CW | PW | SW |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ | 0.001 | -0.0057 | -0.01 | -0.01 | $\begin{aligned} & -0.19 \\ & -0.11 \end{aligned}$ | 0.48 | -0.30 | 0.18 |
| 2 | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ | 0.001 | -0.014 | -0.01 | -0.02 | $\begin{aligned} & -0.58 \\ & -0.23 \end{aligned}$ | 1.22 | -0.81 | 0.41 |
| 3 | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ | 0.5 | -2.58839 | -2.59 | -2.59 | $\begin{aligned} & -67.40 \\ & -52.00 \end{aligned}$ | 218.43 | -119.41 | 99.02 |
| 4 | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ | 0.001 | -0.00775 | -0.01 | -0.01 | $\begin{aligned} & -0.23 \\ & -0.14 \end{aligned}$ | 0.64 | -0.37 | 0.27 |
| 5 | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ | 0.001 | -0.02637 | -0.03 | -0.03 | $\begin{aligned} & -0.95 \\ & -0.10 \end{aligned}$ | 2.16 | -1.05 | 1.10 |
| 6 | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ | 0.5 | -2.4747 | -2.48 | -2.47 | $\begin{aligned} & -58.07 \\ & -82.56 \end{aligned}$ | 202.06 | -140.63 | 61.44 |
| 7 | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ | 0.5 | -3.55014 | -3.55 | -3.55 | $\begin{array}{r} -160.97 \\ -70.07 \end{array}$ | 305.33 | -231.03 | 74.30 |
| 8 | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ | 0.5 | -3.99094 | -3.99 | -3.99 | $\begin{aligned} & -91.25 \\ & -83.21 \end{aligned}$ | 348.13 | -174.46 | 173.67 |
| 9 | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ | 0.5 | -3.6365 | -3.64 | -3.64 | $\begin{array}{r} -97.94 \\ -102.07 \end{array}$ | 305.61 | -200.01 | 105.60 |
| 10 | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ | 0.5 | -3.72095 | -3.72 | $-3.72$ | $\begin{array}{r} -89.78 \\ -192.38 \end{array}$ | 311.02 | -282.17 | 28.86 |

and higher consumer and social welfare in comparison with the NZTS mechanism.
6.1.5. Sensitivity to $d^{\text {SO }}$. To analyze the sensitivity of our results to the value of $d^{\text {SO }}$, we focus on the experiment in Section 6.1.4 with the cost parameters listed in Table 4. To compare the stochastic settlement mechanism with the NZTS, we find the equilibrium values of the SFSP-FD mechanism on a range of different values for $d^{\text {SO }}$. The equilibrium values of the two-period single settlement mechanism and the stochastic settlement mechanism for different $b$ s are listed in Table 5.

This table indicates that our proven results of the symmetric case are expected in this case as well. Firstly, SFSP-FD yields higher social welfare for $d^{\mathrm{SO}} \in$ ( $0, \max _{i}\left\{\delta_{i}\right\}$ ). Secondly, social welfare is increasing with respect to $d^{\mathrm{SO}}$ in this range and reaches its maximum value at a much higher level of $d^{\text {SO }}$ (somewhere between 2 and 3 in this example). After this point, social welfare starts to drop with higher $d^{\text {SO }}$ values and ends up lower than that of the NZTS mechanism for very large values of $d^{\text {SO }}$. The third similarity is that generators submit $b=$ $\varepsilon$ when $d^{\text {SO }}$ is larger than a threshold value.

### 6.2. Restriction to the Case of Supply Functions with Intercept Zero

The model originally used by Green (1996) restricted the linear supply offers to have an intercept at zero.

Table 4. Cost Function of the Generators

| Gen | $\alpha$ | $\beta$ | $\delta$ |
| :--- | ---: | :---: | :--- |
| 1 | 0 | 0.001 | 0.001 |
| 2 | 10 | 1 | 0.5 |

We went through the exercise of constructing NZTS and ISOSP equilibrium results when supply functions comply with the zero intercept rule (note that this eliminates one variable from the decision space of the generators). For this case, we restricted the model to a duopoly. The methodology we have used for this case follows that of the general case. For each market clearing mechanism we establish the values of $q_{i}, f, x_{i, s}$, and $p_{s}$ as before. Then we obtain the expected utility expressions and establish quasiconcavity results for each case following the same lines of argument used in the previous sections.

When restricted by the zero intercept condition, and responding to the opponent restricted by the same condition, the best reply and hence equilibrium values change. Furthermore, we find that in the ISOSP case, we have a unique (symmetric) equilibrium. An interesting observation here is that allowing one more degree of freedom, by the choice of an intercept, leading to a continuum of equilibria, leads the ISO to acknowledge a deviation cost (penalty) for the participants (in efforts to improve welfare). As we observed, for any choice of deviation penalty in $(0, \delta)$, the welfare of ISOSP is improved over NZTS. This is no longer the case for the Green type linear supply functions. That is, the welfare difference between NZTS and ISOSP can be positive or negative. Specifically, if we fix $\beta=2.0, \delta=4.0$, and note $W^{\text {NZTS }}-W^{\text {SS }}$ by TWD, we find the following.

| $Y=5$ | $Y=1.25$ |
| :---: | :---: |
| $\sigma_{Y}^{2}=0.25$ | $\sigma_{Y}^{2}=0.0625$ |
| $\mathrm{Z}=0.5$ | $\mathrm{Z}=0.125$ |
| $T W D=-4.26892$ | $T W D=1.54577$ |

Table 5. Equilibrium Values of SFSP-FD for Different Levels of $d^{\text {SO }}$ in Comparison with the Equilibrium Values of NZTS

| Gen | $d^{\text {SO }}$ | $a$ | $b$ | $b+d$ | CW | PW | SW |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 0.0001 | -0.0569 | 0.6563 | 0.6564 | 3,688.9 | 3,092.4 | 6,781.3 |
| 2 | 0.0001 | -1.0159 | 1.8962 | 1.8963 |  |  |  |
| 1 | 0.001 | -0.0078 | 0.6554 | 0.6564 | 3,689.3 | 3,092.1 | 6,781.4 |
| 2 | 0.001 | -1.0042 | 1.8953 | 1.8963 |  |  |  |
| 1 | 0.01 | 0.4858 | 0.6464 | 0.6564 | 3,693.3 | 3,089.5 | 6,782.8 |
| 2 | 0.01 | -0.8876 | 1.8863 | 1.8963 |  |  |  |
| 1 | 0.1 | 5.4164 | 0.5565 | 0.6565 | 3,735.6 | 3,060.9 | 6,796.5 |
| 2 | 0.1 | 0.2343 | 1.7963 | 1.8963 |  |  |  |
| 1 | 0.5 | 27.2341 | 0.1566 | 0.6566 | 3,993.3 | 2,861.7 | 6,855.0 |
| 2 | 0.5 | 3.7615 | 1.3955 | 1.8955 |  |  |  |
| 1 | 2 | 15.8928 | $\varepsilon$ | 2 | 6,027.3 | 1,782.8 | 7,810.0 |
| 2 | 2 | 14.9124 | 0.1667 | 2.1667 |  |  |  |
| 1 | 3 | 15.7103 | $\varepsilon$ | 3 | 6,022.1 | 1,769.4 | 7,791.5 |
| 2 | 3 | 15.7103 | $\varepsilon$ | 3 |  |  |  |
| 1 | 10 | 36.2862 | $\varepsilon$ | 10 | 3,943.7 | 2,692.3 | 6,636.1 |
| 2 | 10 | 36.2862 | $\varepsilon$ | 10 |  |  |  |
| 1 | 100 | 36.2862 | $\varepsilon$ | 100 | 3,935.2 | 2,620.8 | 6,556.0 |
| 2 | 100 | 36.2862 | $\varepsilon$ | 100 |  |  |  |
| 1 | NZTS | -0.0622 | 0.6567 | NA | 3,688.0 | 3,092.7 | 6,780.7 |
| 2 | NZTS | -1.0199 | 1.8964 | NA |  |  |  |

## 7. Conclusion

In this paper, we set up a simple modelling environment in which we were able to compare the New Zealand inspired two-period single settlement market clearing mechanism against a stochastic settlement auction, which reduces to another two-period single settlement auction with explicit penalties of deviation, therefore different from the NZTS model. We were able to model firms' best responses in these markets, and so find equilibrium behaviour in each. We find that in our symmetric models, the ISOSP-FD auction provably dominates the NZTS auction when measuring expected social welfare.

To test the robustness of our results to the modeling assumptions, we extended our analysis to two other cases. For the case of asymmetric generators, ISOSP-FD outperforms NZTS (assuming that the deviation parameter is chosen appropriately). However, the same results cannot be replicated for a restricted model where affine offers are confined to have intercept zero, and we provide a case for which NZTS has a better performance.

## Endnotes

[^0]${ }^{3}$ Within this five-minute period a frequency keeping generator will match any small changes in demand. We ignore this aspect of the market, as frequency keeping is purchased through a separate market and until recently was procured through annual contracts.
${ }^{4}$ While it may be tidier from an exposition perspective to allow for tranche offers (with fixed price and maximum quantity), such a model would lead to maximum generation constraints, and their dual multipliers, in the ISO's problem. This will in turn impede obtaining an analytical equilibrium expression.
${ }^{5}$ This is a modified version of Pritchard et al. problem. There is only one node and thus no transmission constraints, and demand is elastic.

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# Technical Companion for the Paper "Single and Multi-settlement Approaches to Market Clearing under Demand Uncertainty" 

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## 1 Proposition 4

Proposition. The equilibrium pre-dispatch and spot production quantities of the firms in the NZTS market are non-negative, i.e. $q_{i} \geq 0 \quad \forall i$, and $y_{i, s} \geq 0 \quad \forall i, s$ where $q_{i}$ and $y_{i, s}$ are the optimal solutions to problems (1) and (2) respectively using the equilibrium parameters from (10) and (11) from the main paper.

Proof. To prove the proposition, we first show the equilibrium price intercept of the supply function of generators (i.e. $a_{i}=\frac{A_{i}}{B_{i}}$ ) is less than the price intercept of the demand function (i.e. $Y$ and $Y_{s}$ ). Then we show this property entails the non-negativity of equilibrium quantities.

Substituting $A_{i}$ and $B_{i}$ from Proposition 3 into $a_{i}=\frac{A_{i}}{B_{i}}$, and then taking the derivative of $a_{i}$ with respect to $Z$, we achieve

$$
\frac{\partial a_{i}}{\partial Z}=\frac{2 \delta\left((n-2)^{2} Z+2 k+n(\beta+\delta+k)\right)(Y-\alpha)}{k((n+2) Z+\beta-\delta+k)^{2}}
$$

where $k=\sqrt{(n-2)^{2} Z^{2}+2 n Z(\beta+\delta)+(\beta+\delta)^{2}}$. Because $n \geq 2, Z>0$, $\beta \geq 0, \delta \geq 0$, and $\alpha \leq Y$, we have

$$
\begin{equation*}
\frac{\partial a_{i}}{\partial Z} \geq 0 \tag{1}
\end{equation*}
$$

On the other hand, taking the limit of $a_{i}$ as $Z$ approaches infinity, we obtain

$$
\begin{equation*}
\lim _{Z \rightarrow \infty} a_{i}=\alpha \tag{2}
\end{equation*}
$$

Equations (1) and (2) yield

$$
a_{i} \leq \alpha
$$

This together with assumption $\alpha \leq Y_{s}, \forall s$ yields

$$
\begin{equation*}
a_{i} \leq Y_{s} \quad \forall i, s \tag{3}
\end{equation*}
$$

Using $a_{i}=\frac{A_{i}}{B_{i}}$, we can rewrite equation (3) as

$$
\begin{equation*}
B_{i} Y_{s}-A_{i} \geq 0 \quad \forall i, s \tag{4}
\end{equation*}
$$

Also, using the value of $B_{i}$ from Proposition 3, we can show $B_{i} \geq 0$. Thus, we can conclude

$$
\begin{equation*}
B \geq 0 \tag{5}
\end{equation*}
$$

On the other hand, embedding $p_{s}$ into $y_{i, s}$ from Proposition 2, we obtain

$$
y_{i, s}=\frac{B_{i} Y_{s}-A_{i}}{Z B+1} \quad \forall i, s
$$

This together with equations (4) and (5) and assumption $Z>0$ gives

$$
y_{i, s} \geq 0 \quad \forall i, s
$$

From Propositions 1 and 2, we achieve $q_{i}=\sum_{s} \theta_{s} y_{i, s}$. As $\theta_{s} \geq 0$, we obtain

$$
q_{i} \geq 0
$$

$\forall i$.

## 2 The optimal solution to ISOSP problem: proof of Proposition 5

Proposition. If $(\mathbf{q}, \mathbf{x}, \mathbf{f}, \mathbf{p})$ represents the solution of ISOSP, then we have

$$
\begin{align*}
q_{i} & =\frac{(Y+Z A) B_{i}}{1+Z B}-A_{i}  \tag{6}\\
x_{i, s} & =\frac{\left(Y_{s}-Y\right) R_{i}}{1+Z R}  \tag{7}\\
f & =\frac{Y+Z A}{1+Z B} \\
p_{s} & =\frac{Y+Z A}{1+Z B}+\frac{Y_{s}-Y}{1+Z R} .
\end{align*}
$$

Proof. The Lagrangian function of ISOSP can be represented as follows:

$$
\begin{aligned}
L= & -f\left(-Q+\sum_{i=1}^{n} q_{i}\right) \\
& +\sum_{s=1}^{S} \theta_{s}\left(-p_{s}\left(Q-C_{s}+\sum_{i=1}^{n} x_{i, s}\right)\right. \\
& \left.-Y_{s} C_{s}+\frac{Z C_{s}^{2}}{2}+\sum_{i=1}^{n}\left(\frac{1}{2} d_{i} x_{i, s}^{2}+a_{i}\left(q_{i}+x_{i, s}\right)+\frac{1}{2} b_{i}\left(q_{i}+x_{i, s}\right)^{2}\right)\right)
\end{aligned}
$$

Taking the derivative with respect to different variables yields the following equations.

$$
\begin{gather*}
\frac{\partial L}{\partial q_{i}}=-f+\sum_{s} \theta_{s}\left(a_{i}+b_{i}\left(q_{i}+x_{i, s}\right)\right)  \tag{8}\\
\frac{\partial L}{\partial x_{i, s}}=\theta_{s}\left(-p_{s}+a_{i}+b_{i}\left(q_{i}+x_{i, s}\right)+d_{i} x_{i, s}\right)  \tag{9}\\
\frac{\partial L}{\partial C_{s}}=\theta_{s}\left(p_{s}-Y_{s}+Z C_{s}\right)  \tag{10}\\
\frac{\partial L}{\partial Q}=f-\sum_{s} \theta_{s} p_{s}  \tag{11}\\
\frac{\partial L}{\partial p_{s}}=\theta_{s}\left(-Q+C_{s}-\sum_{i} x_{i, s}\right)  \tag{12}\\
\frac{\partial L}{\partial f}=Q-\sum_{i} q_{i} \tag{13}
\end{gather*}
$$

The Lagrangian is evidently a convex function. Thus, for finding the solution of the stochastic program, we should set all above derivatives to zero. From (8)

$$
\begin{equation*}
f=a_{i}+b_{i} q_{i}+\sum_{s} p_{s} x_{i, s} \tag{14}
\end{equation*}
$$

From (9) and (14)

$$
\begin{equation*}
p_{s}=f+\left(b_{i}+d_{i}\right) x_{i, s} \tag{15}
\end{equation*}
$$

and from (11)

$$
\begin{equation*}
f=\sum_{s} \theta_{s} p_{s} \tag{16}
\end{equation*}
$$

Now (14), (15) and (16) result in the following conclusion, as it is also concluded from Lemma 2.

$$
\begin{equation*}
\sum_{s} \theta_{s} x_{i, s}=0 \tag{17}
\end{equation*}
$$

Equations (14) and (17) lead to

$$
\begin{equation*}
f=a_{i}+b_{i} q_{i} \tag{18}
\end{equation*}
$$

Note that the forward price is solely a function of forward quantities.
From (10),

$$
\begin{equation*}
p_{s}=Y_{s}-Z C_{s} \tag{19}
\end{equation*}
$$

from (12),

$$
\begin{equation*}
C_{s}=Q+\sum_{i} x_{i, s} \tag{20}
\end{equation*}
$$

and from (13),

$$
\begin{equation*}
Q=\sum_{i} q_{i} . \tag{21}
\end{equation*}
$$

Equations (17) and (20) lead to

$$
\begin{equation*}
\sum_{s} \theta_{s} C_{s}=Q \tag{22}
\end{equation*}
$$

Equations (16), (19) and (22) lead to

$$
\begin{equation*}
f=Y-Z Q \tag{23}
\end{equation*}
$$

Now from (18) and (23) we can conclude

$$
\begin{equation*}
q_{i}=\frac{Y-Z Q-a_{i}}{b_{i}} \tag{24}
\end{equation*}
$$

In consequence, using (21), summing $q_{i}$ from (24) over all firms and applying the change of variables from $\left(a_{i}, b_{i}, d_{i}\right)$ to $\left(A_{i}, B_{i}, R_{i}\right)$, we obtain

$$
Q=(Y-Z Q) B-A
$$

Therefore,

$$
\begin{equation*}
Q=\frac{Y B-A}{1+Z B} \tag{25}
\end{equation*}
$$

Now the following inference can be resulted from (24) and (25).

$$
\begin{equation*}
q_{i}=\frac{(Y+Z A) B_{i}}{1+Z B}-A_{i} \tag{26}
\end{equation*}
$$

Now let us find $x_{i, s}$. Equations (15), (19) and (20) give

$$
f+\left(b_{i}+d_{i}\right) x_{i, s}=Y_{s}-Z Q-Z \sum_{i} x_{i, s}
$$

By adding (23) to this equation we obtain

$$
\begin{equation*}
x_{i, s}=\frac{Y_{s}-Y-Z \sum_{i} x_{i, s}}{b_{i}+d_{i}} . \tag{27}
\end{equation*}
$$

Now by getting a summation from (27) and simplifying the resulting equation we achieve

$$
\sum_{i} x_{i, s}=\frac{\left(Y_{s}-Y\right) R}{1+Z R}
$$

By inserting this equation in (27), we obtain

$$
\begin{equation*}
x_{i, s}=\frac{\left(Y_{s}-Y\right) R_{i}}{1+Z R} \tag{28}
\end{equation*}
$$

and from (23) and (25), the first stage price can be extracted:

$$
\begin{equation*}
f=\frac{Y+Z A}{1+Z B} \tag{29}
\end{equation*}
$$

One observation about this equation is that forward price is independent of $R$, in other words, it is independent of the deviating cost in the spot market.

Equations (25), (28) and (29) determine the spot price for each scenario:

$$
\begin{equation*}
p_{s}=\frac{Y+Z A}{1+Z B}+\frac{Y_{s}-Y}{1+Z R} . \tag{30}
\end{equation*}
$$

## 3 The equilibrium of the stochastic settlement market: proof of Proposition 7

Proposition. The unique symmetric equilibrium quantities of ISOSP-FD are as follows.
$b_{i}=\max \left\{\varepsilon, \frac{-Z(n-2)+\beta+\delta+\sqrt{Z^{2}(n-2)^{2}+2 Z n(\beta+\delta)+(\beta+\delta)^{2}}}{2}-d^{S O}\right\}$

$$
\begin{equation*}
a_{i}=\frac{\alpha-Y+B_{i}\left(-Z(Y(n-2)-(2 n-1) \alpha)+Y \beta+Z(n-1)(Z n \alpha+Y \beta) B_{i}\right)}{B_{i}\left(Z(n+1)+\beta+Y(n-1)(Z n+\beta) B_{i}\right)} \tag{31}
\end{equation*}
$$

Proof. To find a symmetric equilibrium, we can use

$$
\begin{aligned}
& B_{-i}=(n-1) B_{i}, \\
& A_{-i}=(n-1) A_{i},
\end{aligned}
$$

and

$$
R_{-i}=(n-1) R_{i} .
$$

By putting these equations in the best response functions (from Theorem 1) and solving the resulting equations with respect to $A_{i}$ and $R_{i}$, we obtain the following equilibrium equations.

$$
\begin{aligned}
& A_{i}=\frac{\alpha-Y+B_{i}\left(-Z(Y(n-2)-(2 n-1) \alpha)+Y \beta+Z(n-1)(Z n \alpha+Y \beta) B_{i}\right)}{Z(n+1)+\beta+Y(n-1)(Z n+\beta) B_{i}} \\
& \quad R_{i}=\min \left\{B_{i}, \frac{2}{-Z(n-2)+\beta+\delta+\sqrt{Z^{2}(n-2)^{2}+2 Z n(\beta+\delta)+(\beta+\delta)^{2}}}\right\}
\end{aligned}
$$

Let us see why equation (31) implies a true equilibrium quantity. Let

$$
\hat{R}_{i}=\frac{2}{-Z(n-2)+\beta+\delta+\sqrt{Z^{2}(n-2)^{2}+2 Z n(\beta+\delta)+(\beta+\delta)^{2}}}
$$

If $\hat{R}_{i} \leq B_{i}$, it satisfies the best response function for $R_{i}$. When $\hat{R}_{i}>B_{i}$, we need to show

$$
\frac{1+Z(n-1) B_{i}}{Z+\beta+\delta+Z(n-1)(\beta+\delta) B_{i}} \geq B_{i}
$$

It means when the other generators $j$ have chosen $R_{j}=B_{j}$, the best response for the firm $i$ is also to choose $R_{i}=B_{i}$. Note that $B_{i}$ is a fixed quantity chosen by the ISO, Thus, $B_{j}=B_{i}$. Now define

$$
f(x)=\frac{1+Z(n-1) x}{Z+\beta+\delta+Z(n-1)(\beta+\delta) x}-x .
$$

We can easily show that $f(x)$ is a concave function for $x \geq 0$ :

$$
f^{\prime \prime}(x)=-\frac{2 Z^{3}(n-1)^{2}(\beta+\delta)}{(Z+\beta+\delta+Z(n-1)(\beta+\delta) x)^{3}}<0
$$

Also $f(0)=\frac{1}{Z+\beta+\delta}>0$ and $f\left(\hat{R}_{i}\right)=0$. Thus for $0<B_{i}<\hat{R}_{i}$, and by considering concavity of $f(x)$, we obtain $f\left(B_{i}\right) \geq 0$. Therefore

$$
\frac{1+Z(n-1) B_{i}}{Z+\beta+\delta+Z(n-1)(\beta+\delta) B_{i}} \geq B_{i}
$$

## 4 Stochastic settlement yields non-negative equilibria: proof of Proposition 8

Proposition. Let $\left(\mathbf{q}^{*}, \mathbf{x}^{*}\right)$ represent an equilibrium of ISOSP-FD. Then the following inequalities hold.

$$
\begin{gathered}
\forall i, s: q_{i}^{*}+x_{i, s}^{*} \geq 0 \\
\forall i: q_{i}^{*} \geq 0
\end{gathered}
$$

Proof. From (26) and (28), the following equation can be derived:

$$
y_{i, s}=q_{i}^{*}+x_{i, s}^{*}=\frac{(Y+Z A) B_{i}}{1+Z B}-A_{i}+\frac{\left(Y_{s}-Y\right) R_{i}}{(1+Z R)} .
$$

It is obvious that if $y_{i, s}$ is non-negative for the scenario that has the lowest $Y_{s}$, it is non-negative for the other scenarios as well. Thus, we prove this only for
the scenario $s^{\prime}$ for which we have $Y_{s^{\prime}} \leq Y_{s}$ for all $s$. If we assume having at least two different scenarios with positive probabilities, we have

$$
\begin{equation*}
Y_{s^{\prime}}<Y \tag{33}
\end{equation*}
$$

Let us first define

$$
\hat{R}_{i}=\frac{2}{-Z(n-2)+\beta+\delta+\sqrt{Z^{2}(n-2)^{2}+2 Z n(\beta+\delta)+(\beta+\delta)^{2}}}
$$

Now consider $y_{i, s^{\prime}}^{\prime}=\min _{\alpha, \delta} y_{i, s^{\prime}}$. Obviously if we prove that $y_{i, s^{\prime}}^{\prime}$ is non-negative, we have also proven the non-negativity of $y_{i, s}$. Now $y_{i, s}$ satisfies

$$
\begin{aligned}
& \frac{\partial y_{i, s^{\prime}}}{\partial \delta}=\left\{\begin{array}{l}
\text { if } \hat{R}_{i} \leq B_{i}: \\
\frac{2\left(Z n+\beta+\delta+\sqrt{Z^{2}(n-2)^{2}+2 Z n(\beta+\delta)+(\beta+\delta)^{2}}\right)\left(Y-Y_{s}\right)}{\sqrt{Z^{2}(n-2)^{2}+2 Z n(\beta+\delta)+(\beta+\delta)^{2}}\left(Z(n+2)+\beta+\delta+\sqrt{Z^{2}(n-2)^{2}+2 Z n(\beta+\delta)+(\beta+\delta)^{2}}\right)^{2}} \\
\text { Otherwise: } \\
0 .
\end{array}\right. \\
& \frac{\partial y_{i, s^{\prime}}}{\partial \alpha}=-\frac{1+Z B_{1}(n-1)}{Z(n+1)+\beta+Z B_{1}(n-1)(Z n+\beta)} .
\end{aligned}
$$

The parameters $Z, \beta$, and $\delta$ are non-negative. Thus from (33) we can conclude

$$
\begin{aligned}
\frac{\partial y_{i, s}}{\partial \delta} & \geq 0 \\
\frac{\partial y_{i, s}}{\partial \alpha} & \leq 0
\end{aligned}
$$

Consequently, $\delta=0$ and $\alpha=Y_{s^{\prime}}$ minimize $y_{i, s^{\prime}}$. Note that we have assumed that the $y$-intercept of the cost function $\alpha$ is less than the $y$-intercept of the demand scenarios $Y_{s^{\prime}}$. Thus, we prove that $y_{i, s^{\prime}}^{\prime}=y_{i, s^{\prime}}\left(\delta=0, \alpha=Y_{s^{\prime}}\right)$ takes non-negative values.

When $\delta=0$, at $\hat{\beta}=\frac{1+Z B_{i}(n-2)}{B_{i}\left(1+Z B_{i}(n-1)\right)}$, we have $\hat{R}_{i}=B_{i}$. By applying the fact that $\hat{R}_{i}$ is a decreasing function of $\beta$, we can conclude

$$
R_{i}= \begin{cases}B_{i} & \beta<\hat{\beta} \\ \hat{R}_{i} & \beta \geq \hat{\beta}\end{cases}
$$

and

$$
y_{i, s^{\prime}}^{\prime}= \begin{cases}\frac{(Y+Z A) B_{i}}{1+Z B}-A_{i}+\frac{\left(Y_{s}-Y\right) B_{i}}{(1+Z B)} & \text { if } \beta<\hat{\beta} \\ \frac{(Y+Z A) B_{i}}{1+Z B}-A_{i}+\frac{\left(Y_{s}-Y\right) \hat{R}_{i}}{(1+Z \hat{R})} & \text { if } \beta \geq \hat{\beta} .\end{cases}
$$

We can also show that equation $y_{i, s^{\prime}}^{\prime}=0$ only holds at $\beta=\hat{\beta}$. In addition, $y_{i, s^{\prime}}^{\prime}$ is a continuous function. These mean $y_{i, s^{\prime}}^{\prime}$ is either entirely positive or entirely negative in each of $[0, \hat{\beta}]$ or $[\hat{\beta}, \infty)$. Firstly, we prove that it is positive in $[0, \hat{\beta}]$.

We see that $\frac{\partial y_{i, s^{\prime}}^{\prime}}{\partial A_{i}}<0$. On the other hand,

$$
\frac{\partial A_{i}}{\partial \beta}=\frac{(Y-\alpha)\left(1+Z(n-1) B_{i}\right)^{2}\left(1+Z n B_{i}\right)}{\left(Z(n+1)+\delta+Z(n-1)(Z n+\beta) B_{i}\right)^{2}} \geq 0
$$

Therefore, for $\beta<\hat{\beta}, \frac{\partial y_{i, s^{\prime}}^{\prime}}{\partial \beta}=\frac{\partial y_{i, s^{\prime}}^{\prime}}{\partial A_{i}} \frac{\partial A_{i}}{\partial \beta}$ is not positive. It means $y_{i, s^{\prime}}$ is a nonincreasing function of $\beta$ in this interval. Considering the fact that $y_{i, s^{\prime}}^{\prime}(\hat{\beta})=0$, we can conclude

$$
\begin{equation*}
y_{i, s^{\prime}}^{\prime} \geq 0 \text { if } \beta \leq \hat{\beta} \tag{34}
\end{equation*}
$$

The right derivative of $y_{i, s^{\prime}}^{\prime}$ at $\hat{\beta}$ also has a positive value of
$\frac{Z^{2}\left(Y-Y_{s}\right) B_{i}(n-1)\left(1+Z(n-1) B_{i}\right)\left(1+Z n B_{i}\right)^{2}}{\sqrt{Z^{2}(n-2)^{2}+2 Z n \beta+\delta^{2}}\left(Z(n+1)+\delta+Z B_{i}\left(-\beta+2 n(Z n+\beta)+Z(n-1) n(Z n+\beta) B_{i}\right)\right)^{2}}$.
If we add this to the facts that $y_{i, s^{\prime}}^{\prime}(\hat{T})=0$ and $y_{i, s^{\prime}}^{\prime}$ is either entirely nonnegative or entirely non-positive for $\beta>\hat{\beta}$, we can conclude that

$$
\begin{equation*}
y_{i, s^{\prime}}^{\prime} \geq 0, \text { if } \beta \geq \hat{\beta} \tag{35}
\end{equation*}
$$

Equations (34) and (35) can be gathered to conclude

$$
y_{i, s^{\prime}}^{\prime} \geq 0
$$

Therefore

$$
y_{i, s}=q_{i}^{*}+x_{i, s}^{*} \geq 0
$$

We know from Lemma 2 that $x_{i, s}^{*}$ is non-positive for at least one-scenario. Thus $q_{i}^{*} \geq 0$.

## 5 Equilibrium of the stochastic settlement mechanism with non-negativity constraints: Theorem 3

To prove Theorem 3, we consider three different but closely related optimization problems (for a specified firm). These are:

1. WONN: The optimization problem of a generator assuming that the nonnegativity constraints are not contained in the market clearing problem. The optimal solution to this problem (assuming that the other generators offer the equilibrium values for ISOSP, given in the paper) is the equilibrium offer strategy for this firm under ISOSP.
2. WNN: The optimization problem of a generator assuming that the nonnegativity constraints are imposed for the market clearing problem.
3. RWNN: This is a relaxed version of WNN. We remove the orthogonality constraints $e_{i, s}\left(q_{i}+x_{i, s}\right)=0$ for any firm $i$, and non-negativity constraints $q_{i}+x_{i, s} \geq 0$ for all non-optimizing firms $(i \neq j)$.

We wish to establish that the optimal solution to WONN remains optimal for WNN. The feasible sets of these problems contain the optimal solutions of the ISO's problem. Since ISO's problem is different with and without nonnegativity constraints, there are points (i.e. a vector of decisions variables such as offers, prices, dispatch quantities) feasible only for WNN, and points feasible only for WONN. Therefore, if we show that the optimal solution to WONN is also feasible in WNN, it does not suffice to prove the theorem, since there are other feasible solutions of WNN that are not investigated in WONN. This makes it difficult to present an intuitive proof for the theorem. To prove the theorem, we use Lemma 5.3 to show that the optimal solution to WONN is also the optimal solution to RWNN. Then, in the proof of Theorem 3, we establish that this point is also a feasible solution to WNN. Since it is optimal for the relaxed problem and it is feasible in the more constrained WNN problem, this point is also the optimal solution to WNN. Therefore, it is also the equilibrium point of ISOSP with non-negativity constraints. Lemmas 5.1 and 5.2 are technical lemmas that help establish the main lemma, Lemma 5.3. Lemma 5.3 is the only lemma that is directly used in the proof of Theorem 3.

### 5.1 ISOSP clearing problem with non-negativity constraints

The SP clearing problem with non-negativity constraints is
ISOSP :

$$
\begin{aligned}
\min z= & \sum_{s=1}^{S} \theta_{s}\left(\sum_{i=1}^{n}\left[a_{i}\left(q_{i}+x_{i, s}\right)+\frac{b}{2}\left(q_{i}+x_{i, s}\right)^{2}+\frac{d_{i}}{2} x_{i, s}^{2}\right]-\left(Y_{s} C_{s}-\frac{Z}{2} C_{s}^{2}\right)\right) \\
\text { s.t. } & \sum_{i} q_{i}-Q=0 \\
& Q+\sum_{i} x_{i, s}-C_{s}=0 \quad \forall s \in\{1, \ldots, S\} \\
& q_{i}+x_{i, s} \geq 0 \quad \forall i \in\{1, \ldots, n\}, \forall s \in\{1, \ldots, S\}
\end{aligned}
$$

ISOSP is a convex optimization problem as the objective function of ISOSP is a convex function, and its constraints are linear. Therefore, solving the KKT conditions of this problem is equivalent to solving ISOSP.

### 5.1.1 KKT of ISOSP

To find the KKT conditions we can use the Lagrangian function

$$
\begin{aligned}
L=\sum_{s=1}^{S}\left(\theta _ { s } \left(\sum _ { i = 1 } ^ { n } \left(a_{i}\left(x_{i, s}+q_{i}\right)\right.\right.\right. & \left.+\frac{b}{2}\left(x_{i, s}+q_{i}\right)^{2}+\frac{d_{i}}{2} x_{i, s}^{2}\right) \\
-\left(C_{s} Y_{s}-\frac{Z C_{s}^{2}}{2}\right) & \left.+p_{s}\left(Q+\sum_{i=1}^{n} x_{i, s}-C_{s}\right)\right) \\
& \left.-\sum_{i=1}^{n} e_{i, s}\left(x_{i, s}+q_{i}\right)\right)-f\left(\sum_{i=1}^{n} q_{i}-Q\right) .
\end{aligned}
$$

To produce the building blocks of the KKT condition, we can use the partial derivatives of $L$ with respect to the decision variables.

$$
\begin{aligned}
& \frac{\partial L}{\partial q_{i}}=-f-\sum_{s=1}^{S} e_{i, s}+\left(a_{i}+b q_{i}\right)+b \sum_{s=1}^{S} \theta_{s} x_{i, s} \\
& \frac{\partial L}{\partial x_{i, s}}=-e_{i, s}+\theta_{s}\left(-p_{s}+a_{i}+b q_{i}+\left(b+d_{i}\right) x_{i, s}\right) \\
& \frac{\partial L}{\partial C_{s}}=\left(p_{s}+Z C_{s}-Y_{s}\right) \theta_{s} \\
& \frac{\partial L}{\partial Q}=f-\sum_{s} \theta_{s} p_{s} \\
& \frac{\partial L}{\partial p_{s}}=\theta_{s}\left(C_{s}-\left(Q+\sum_{i=1}^{n} x_{i, s}\right)\right) \\
& \frac{\partial L}{\partial f}=Q-\sum_{i=1}^{n} q_{i} \\
& \frac{\partial L}{\partial e_{i, s}}=-q_{i}-x_{i, s}
\end{aligned}
$$

Thus, KKT of this problem can be represented as

$$
\begin{array}{lll}
-f-\sum_{s=1}^{S} e_{i, s}+\left(a_{i}+b q_{i}\right)+b \sum_{s=1}^{S} \theta_{s} x_{i, s}=0 & \forall i \in\{1, \ldots, n\} & {[\mathrm{C} 1]} \\
Q=\sum_{i=1}^{n} q_{i} & & {[\mathrm{C} 2]} \\
C_{s}=\left(Q+\sum_{i=1}^{n} x_{i, s}\right) & \forall s \in\{1, \ldots, S\} & {[\mathrm{C} 3]} \\
p_{s}=\left(Y_{s}-Z C_{s}\right) & \forall s \in\{1, \ldots, S\} & {[\mathrm{C} 4]} \\
f=\sum_{s=1}^{S} \theta_{s} p_{s} & & {[\mathrm{C} 5]} \\
e_{i, s}=\theta_{s}\left(-p_{s}+a_{i}+b q_{i}+\left(b+d_{i}\right) x_{i, s}\right) & \forall i \in\{1, \ldots, n\} & {[\mathrm{C} 6]} \\
e_{i, s}\left(q_{i}+x_{i, s}\right)=0 & \forall s \in\{1, \ldots, S\} & \\
e_{i, s} \geq 0 & \forall i \in\{1, \ldots, n\} & {[\mathrm{C} 7]} \\
q_{i}+x_{i, s} \geq 0 & \forall s \in\{1, \ldots, S\} & \\
& \forall i \in\{1, \ldots, n\} & {[\mathrm{C} 8]}  \tag{C8}\\
& \forall s \in\{1, \ldots, S\} & \\
& \forall i \in\{1, \ldots, n\} & {[\mathrm{C} 9]} \\
& \forall s \in\{1, \ldots, S\} . &
\end{array}
$$

If we replace the value of $f$ and $e_{i, s}$ from [C5] and [C6] into [C1], constraint [C1] can be replaced with $\sum_{s=1}^{S} \theta_{s} x_{i, s}=0$.

### 5.1.2 Firms' optimisation problem

Problem WNN $[j]$ represents the optimization problem solved by firm $j$ to maximize its profit, subject to KKT conditions of ISO's optimization problem.

WNN[j]:

$$
\begin{aligned}
\max u_{j}= & \sum_{s=1}^{S} \theta_{s}\left(p_{s}\left(q_{j}+x_{j, s}\right)-\right. \\
& \left.\left(\alpha_{j}\left(q_{j}+x_{j, s}\right)+\frac{\beta_{j}}{2}\left(q_{j}+x_{j, s}\right)^{2}+\frac{\delta_{j}}{2} x_{j, s}^{2}\right)\right)
\end{aligned}
$$

$$
\text { s.t. } \quad \sum_{s=1}^{S} \theta_{s} x_{i, s}=0
$$

$$
\forall i \in\{1, \ldots, n\}
$$

$$
Q=\sum_{i=1}^{n} q_{i}
$$

$$
C_{s}=\left(Q+\sum_{i=1}^{n} x_{i, s}\right)
$$

$$
p_{s}=\left(Y_{s}-Z C_{s}\right)
$$

$$
f=\sum_{s=1}^{S} \theta_{s} p_{s}
$$

$$
e_{i, s}=\theta_{s}\left(-p_{s}+a_{i}+b q_{i}+\left(b+d_{i}\right) x_{i, s}\right)
$$

$$
e_{i, s}\left(q_{i}+x_{i, s}\right)=0
$$

$$
e_{i, s} \geq 0
$$

$$
q_{i}+x_{i, s} \geq 0
$$

WNN to the following shape.
WNN[j]:

$$
\begin{array}{ll}
\max u_{j}=\sum_{s=1}^{S} \theta_{s}\left(p_{s}\left(q_{j}+x_{j, s}\right)-\right. & \\
\left.\qquad\left(\alpha_{j}\left(q_{j}+x_{j, s}\right)+\frac{\beta_{j}}{2}\left(q_{j}+x_{j, s}\right)^{2}+\frac{\delta_{j}}{2} x_{j, s}^{2}\right)\right) & \\
\text { s.t. } \sum_{s=1}^{S} \theta_{s} x_{i, s}=0 & \forall i \in\{1, \ldots, n\} \quad \text { [C1] } \\
p_{s}=Y_{s}-Z\left(\sum_{h=1}^{n} q_{h}+\sum_{h=1}^{n} x_{h, s}\right) & \forall s \in\{1, \ldots, S\} \quad[\mathrm{C} 4] \\
e_{i, s}=-\theta_{s}\left(-p_{s}+a_{i}+b q_{i}+\left(b+d_{i}\right) x_{i, s}\right) & \forall i \in\{1, \ldots, n\} \quad[\mathrm{C} 6] \\
& \forall s \in\{1, \ldots, S\} \\
e_{i, s}\left(q_{i}+x_{i, s}\right)=0 & \forall i \in\{1, \ldots, n\} \quad[\mathrm{C} 7] \\
& \forall s \in\{1, \ldots, S\} \\
e_{i, s} \geq 0 & \forall i \in\{1, \ldots, n\} \quad[\mathrm{C} 8] \\
& \forall s \in\{1, \ldots, S\} \\
q_{i}+x_{i, s} \geq 0 & \forall i \in\{1, \ldots, n\} \\
& \quad[\mathrm{C} 9] \\
& \forall s \in\{1, \ldots, S\}
\end{array}
$$

With a similar process, the optimization problem of firm $j$ in a stochastic market clearing mechanism without non-negativity constraints can be found as

WONN[j]:

$$
\begin{array}{ll}
\max u_{j}=\sum_{s=1}^{S} \theta_{s}\left(p_{s}\left(q_{j}+x_{j, s}\right)-\right. & \\
\left.\quad\left(\alpha_{j}\left(q_{j}+x_{j, s}\right)+\frac{\beta_{j}}{2}\left(q_{j}+x_{j, s}\right)^{2}+\frac{\delta_{j}}{2} x_{j, s}^{2}\right)\right) & \\
\text { s.t. } \quad \sum_{s=1}^{S} \theta_{s} x_{i, s}=0 & \forall i \in\{1, \ldots, n\} \quad \text { [C1] } \\
p_{s}=Y_{s}-Z\left(\sum_{h=1}^{n} q_{h}+\sum_{h=1}^{n} x_{h, s}\right) & \forall s \in\{1, \ldots, S\} \quad[\mathrm{C} 4]  \tag{C4}\\
e_{i, s}=\theta_{s}\left(-p_{s}+a_{i}+b q_{i}+\left(b+d_{i}\right) x_{i, s}\right) & \forall i \in\{1, \ldots, n\} \quad[\mathrm{C} 6] \\
e_{i, s}=0 & \forall i \in\{1, \ldots, n\} \\
& \quad \forall \mathrm{C} 11] \\
& \forall s \in\{1, \ldots, S\}
\end{array}
$$

Also, we introduce a relaxation to WNN, which we use later in proofs of our theorems. We eliminate constraint [C7]: $e_{i, s}\left(q_{i}+x_{i, s}\right)=0$, and limit the con-
straint [C9]: $\forall i, q_{i}+x_{i, s} \geq 0$ to the optimizer generator $j$ to obtain a relaxation problem as follows.

RWNN:

$$
\begin{align*}
& \max u_{j}=\sum_{s=1}^{S} \theta_{s}\left(p_{s}\left(q_{j}+x_{j, s}\right)-\right. \\
& \left.\left(\alpha_{j}\left(q_{j}+x_{j, s}\right)+\frac{\beta_{j}}{2}\left(q_{j}+x_{j, s}\right)^{2}+\frac{\delta_{j}}{2} x_{j, s}{ }^{2}\right)\right) \\
& \text { s.t. } \sum_{s=1}^{S} \theta_{s} x_{i, s}=0 \quad \forall i \in\{1, \ldots, n\}  \tag{C1}\\
& p_{s}=Y_{s}-Z\left(\sum_{h=1}^{n} q_{h}+\sum_{h=1}^{n} x_{h, s}\right) \quad \forall s \in\{1, \ldots, S\}  \tag{C4}\\
& f=\sum_{s=1}^{S} \theta_{s} p_{s}  \tag{C5}\\
& e_{i, s}=\theta_{s}\left(-p_{s}+a_{i}+b q_{i}+\left(b+d_{i}\right) x_{i, s}\right) \quad \forall i \in\{1, \ldots, n\}  \tag{C6}\\
& \forall s \in\{1, \ldots, S\} \\
& \forall i \in\{1, \ldots, n\} \quad[\mathrm{C} 8]  \tag{C8}\\
& \forall s \in\{1, \ldots, S\} \quad[\mathrm{C} 12] \\
& \text { [C12] }
\end{align*}
$$

Now, we prove three lemmas which help us to demonstrate the final theorem.
Lemma 5.1. If for every $i \neq j(j$ is the optimizer generator $), a_{i}$ and $d_{i}$ has the same value, then the constraint $e_{i, s} \geq 0$ (for every $i \neq j$ ) in RWNN can be replaced with $e_{i, s}=0$ without reducing the optimal value of RWNN.

Proof. We prove the lemma by contradiction. Assume there exist a point $\nu=$ $\left(a_{j}, d_{j}, \boldsymbol{q}, \boldsymbol{x}, \boldsymbol{p}, \boldsymbol{e}\right)$ with at least one $e_{i^{\prime}, s^{\prime}}>0(i \neq j)$ and higher objective value than any feasible solution with $\boldsymbol{e}=\mathbf{0}$.

Consider $\nu^{\prime}=\left(a_{j}^{\prime}, d_{j}^{\prime}, \boldsymbol{q}^{\prime}, \boldsymbol{x}^{\prime}, \boldsymbol{p}^{\prime}, \boldsymbol{e}^{\prime}\right)$ defined as follows.

$$
\begin{align*}
q_{i}^{\prime}= & \begin{cases}q_{i} & i=j \\
q_{i}+\frac{\frac{Z \sum_{h \neq j} \sum_{w} e_{h, w}}{Z(n-1)+b}-\sum_{w} e_{i, w}}{b} & i \neq j\end{cases}  \tag{36}\\
x_{i, s}^{\prime}= & \begin{cases}x_{i, s} & i=j \\
x_{i, s}+\frac{\sum_{w} e_{i, w}-\frac{e_{i, s}}{\theta_{s}}}{b+d_{i}}-\frac{Z\left(\sum_{h \neq j} \sum_{w} e_{h, w}-\sum_{h \neq j} \frac{e_{h, s}}{\theta_{s}}\right)}{\left(Z(n-1)+b+d_{i}\right)\left(b+d_{i}\right)} & i \neq j\end{cases}  \tag{37}\\
a_{j}^{\prime} \geq & \max _{s}\left\{Z \left(\sum_{h \neq j} \sum_{w} e_{h, w}\left(\frac{1}{Z(n-1)+b}-\frac{1}{Z(n-1)+b+d_{i}}\right)\right.\right. \\
& \left.\left.+\frac{\sum_{h \neq j} \frac{e_{h, s}}{\theta_{s}}}{Z(n-1)+b+d_{i}}\right)+a_{j}\right\}  \tag{38}\\
d_{j}^{\prime}= & d_{j} \tag{39}
\end{align*}
$$

Firstly, we show this is a feasible solution.
$\sum_{s} \theta_{s} x_{i, s}^{\prime}= \begin{cases}\sum_{s} \theta_{s} x_{i, s} & i=j \\ \sum_{s} \theta_{s} x_{i, s}+\frac{\sum_{w} e_{i, w}-\sum_{s} \theta_{s} \frac{e_{i, s}}{\theta_{s}}}{b+d_{i}}-\frac{Z\left(\sum_{h \neq j} \sum_{w} e_{h, w}-\sum_{s} \theta_{s} \sum_{h \neq j} \frac{\left.e_{h, s}\right)}{\theta_{s}}\right)}{\left(Z(n-1)+b+d_{i}\right)\left(b+d_{i}\right)} & i \neq j\end{cases}$
Extra simplifications yield

$$
\begin{equation*}
\sum_{s} \theta_{s} x_{i, s}^{\prime}=0 \quad \forall i \tag{40}
\end{equation*}
$$

After substituting the value of $q_{h}^{\prime}$ from (36) into $\sum_{h \neq j} q_{h}^{\prime}$ and slightly simplifying the resulted equation, we get

$$
\begin{equation*}
\sum_{h \neq j} q_{h}^{\prime}=\sum_{h \neq j} q_{h}-\frac{\sum_{h \neq j} \sum_{w} e_{h, w}}{Z(n-1)+b} \tag{41}
\end{equation*}
$$

The same analysis on equation (37) gives us the following equation:

$$
\begin{equation*}
\sum_{h \neq j} x_{h, s}^{\prime}=\sum_{h \neq j} x_{h, s}+\frac{\sum_{h \neq j} \sum_{w} e_{h, w}-\sum_{h \neq j} \frac{e_{h, s}}{\theta_{s}}}{Z(n-1)+b+d_{i}} . \tag{42}
\end{equation*}
$$

The quantity $p_{s}^{\prime}$ can be obtained combining equations [C4], (41), and (42).

$$
\begin{align*}
p_{s}^{\prime}= & p_{s}-Z\left(-\frac{\sum_{h \neq j} \sum_{w} e_{h, w}}{Z(n-1)+b}+\frac{\sum_{h \neq j} \sum_{w} e_{h, w}-\sum_{h \neq j} \frac{e_{h, s}}{\theta_{s}}}{Z(n-1)+b+d_{i}}\right) \\
= & p_{s}+Z\left(\sum_{h \neq j} \sum_{w} e_{h, w}\left(\frac{1}{Z(n-1)+b}-\frac{1}{Z(n-1)+b+d_{i}}\right)\right.  \tag{43}\\
& \left.+\frac{\sum_{h \neq j} \frac{e_{h, s}}{\theta_{s}}}{Z(n-1)+b+d_{i}}\right)
\end{align*}
$$

Considering the fact that $e_{i, s}, Z, b$, and $d_{i}$ have non-negative values,

$$
\begin{equation*}
p_{s}^{\prime} \geq p_{s} \tag{44}
\end{equation*}
$$

From (36), (37), (43), and [C6], $e_{i, s}$ can be obtained as follows.

$$
e_{i, s}^{\prime}= \begin{cases}e_{i, s}+\theta_{s}\left(-p_{s}^{\prime}+p_{s}+a_{j}^{\prime}-a_{j}\right) & i=j \\ e_{i, s}+\theta_{s}\left(-Z \sum_{h \neq j} \sum_{w} e_{h, w}\left(\frac{1}{Z(n-1)+b}-\frac{1}{Z(n-1)+b+d_{i}}\right)\right. & i \neq j \\ \quad-Z \frac{\sum_{h \neq j} \frac{e_{h, s}}{\theta_{s}}}{Z(n-1)+b+d_{i}}+\frac{Z \sum_{h \neq j} \sum_{w} e_{h, w}}{Z(n-1)+b}-\sum_{w} e_{i, w} \\ \left.\quad+\sum_{w} e_{i, w}-\frac{e_{i, s}}{\theta_{s}}-\frac{Z\left(\sum_{h \neq j} \sum_{w} e_{h, w}-\sum_{h \neq j} \frac{e_{h, s}}{\theta_{s}}\right)}{Z(n-1)+b+d_{i}}\right)\end{cases}
$$

This simplifies to

$$
e_{i, s}^{\prime}= \begin{cases}e_{j, s}^{\prime} \geq 0 & i=j \\ 0 & i \neq j\end{cases}
$$

Thus, the constraint [C8] is also satisfied. As $q_{j}^{\prime}=q_{j}, x_{j, s}^{\prime}=x_{j, s}$, and $\nu$ is a feasible solution, constraints [C12] are also fulfilled. In sum, $\nu^{\prime}$ is a feasible solution.

On the other hand, a comparison between the $u_{j}^{\prime}$ and $u_{j}$ demonstrates that $\nu^{\prime}$ gives a better objective:

$$
u_{j}^{\prime}-u_{j}=\sum_{s} \theta_{s}\left(p_{s}^{\prime}-p_{s}\right)\left(q_{j}+x_{j, s}\right)
$$

With $q_{j}+x_{j, s} \geq 0$, as concluded from [C12], and $p_{s}^{\prime}-p_{s} \geq 0$ as resolved in (44)

$$
u_{j}^{\prime} \geq u_{j}
$$

This contradicts the initial assumption, which proves the lemma.
Lemma 5.2. RWNN can be simplified to the following optimization problem.

RWNN:

$$
\begin{array}{lll}
\max u_{j}= & f q_{j}+\sum_{s=1}^{S} \theta_{s}\left(p_{s}-f\right) x_{j, s} & \\
& \quad-\left(\alpha_{j} q_{j}+\frac{\beta_{j}}{2} q_{j}^{2}+\frac{\beta_{j}+\delta_{j}}{2} \sum_{s=1}^{S} \theta_{s} x_{j, s}^{2}\right) & \\
\text { s.t. } \sum_{s=1}^{S} \theta_{s} x_{i, s}=0 & \forall i \in\{1, \ldots, n\} & \text { [C1] } \\
p_{s}=Y_{s}-Z\left(\sum_{h=1}^{n} q_{h}+\sum_{h=1}^{n} x_{h, s}\right) & \forall s \in\{1, \ldots, S\} & \text { [C4] } \\
& & \\
f=\sum_{s=1}^{S} \theta_{s} p_{s} & & \text { [C5] } \\
e_{i, s}=\theta_{s}\left(-p_{s}+a_{i}+b q_{i}+\left(b+d_{i}\right) x_{i, s}\right) & \forall i \in\{1, \ldots, n\} & \text { [C6] } \\
e_{i, s} \geq 0 & \forall s \in\{1, \ldots, S\} & \\
q_{j}+x_{j, s} \geq 0 & \forall i \in\{1, \ldots, n\} & \text { [C8] } \\
& \forall s \in\{1, \ldots, S\} & {[C 12]}
\end{array}
$$

Proof. The first part of the objective function is the optimizer's income, which is equal to

$$
\begin{array}{rlr}
\sum_{s=1}^{S} \theta_{s} p_{s}\left(q_{j}+x_{j, s}\right) & =\sum_{s=1}^{S} \theta_{s} p_{s} q_{j}+\sum_{s=1}^{S} \theta_{s} p_{s} x_{j, s} & \\
& =f q_{j}+\sum_{s=1}^{S} \theta_{s} f x_{j, s}+\sum_{s=1}^{S} \theta_{s}\left(p_{s}-f\right) x_{j, s} & \text { From [C5] } \\
& =f q_{j}+\sum_{s=1}^{S} \theta_{s}\left(p_{s}-f\right) x_{j, s}+f \sum_{s=1}^{S} \theta_{s} x_{j, s} & \\
& =f q_{j}+\sum_{s=1}^{S} \theta_{s}\left(p_{s}-f\right) x_{j, s} . & \text { From [C1] } \tag{C1}
\end{array}
$$

The rest of the objective function can also be simplified similarly, as follows.

$$
\begin{aligned}
\text { Generating Cost }= & \sum_{s=1}^{S} \theta_{s}\left(\alpha_{j}\left(q_{j}+x_{j, s}\right)+\frac{\beta_{j}}{2}\left(q_{j}+x_{j, s}\right)^{2}+\frac{\delta_{j}}{2} x_{j, s}^{2}\right) \\
= & \alpha_{j} q_{j}+\frac{\beta_{j}}{2} q_{j}^{2}+\frac{\beta_{j}+\delta_{j}}{2} \sum_{s=1}^{S} \theta_{s} x_{j, s}^{2} \\
& +\left(\alpha_{j}+\beta_{j} q_{j}\right) \sum_{s=1}^{S} \theta_{s} x_{j, s} \\
= & \alpha_{j} q_{j}+\frac{\beta_{j}}{2} q_{j}^{2}+\frac{\beta_{j}+\delta_{j}}{2} \sum_{s=1}^{S} \theta_{s} x_{j, s}^{2} .
\end{aligned}
$$

From [C1]

Lemma 5.3. If for every $i \neq j\left(j\right.$ is the optimizer generator), $a_{i}$ and $d_{i}$ has the same value, then the optimal solution to WONN is at least as good as the optimal value to $R W N N$.

Proof. To prove the lemma, we find the optimal solution to RWNN, while we ignore the non-negativity constraint $q_{j}+x_{j, s} \geq 0$. Thus, this point gives an objective value as good as (possibly better than) the optimal point. Then we show this point is a feasible solution for WONN, which proves the lemma.

From Lemma 5.2 we have

$$
e_{i, s}=\theta_{s}\left(-Y_{s}+Z\left(\sum_{h=1}^{n} q_{h}+\sum_{h=1}^{n} x_{h, s}\right)+a_{i}+b q_{i}+\left(b+d_{i}\right) x_{i, s}\right) .
$$

To simplify the equations we use some transformations. Let $R_{i}=\frac{1}{\left(b+d_{i}\right)}$, and $A_{i}=\frac{a_{i}}{b}$. Also, let $A$ and $R$ denote $\sum_{h=1}^{n} A_{h}$, and $\sum_{h=1}^{n} R_{h}$ respectively. Then, constraint [C6] looks like

$$
\begin{equation*}
e_{i, s}=\theta_{s}\left(-Y_{s}+Z\left(\sum_{h=1}^{n} q_{h}+\sum_{h=1}^{n} x_{h, s}\right)+\frac{1}{R_{i}} x_{i, s}+b\left(A_{i}+q_{i}\right)\right) . \tag{45}
\end{equation*}
$$

A summation over different scenarios gives

$$
\begin{equation*}
\sum_{w=1}^{S} e_{i, w}=-Y+Z \sum_{h=1}^{n} q_{i}+\left(A_{i}+q_{i}\right) b \tag{46}
\end{equation*}
$$

From Lemma 5.1, the constraints $e_{i, s}=0$ for every $i \neq j$ and $s$ can be replaced with $e_{i, s} \geq 0$ in RWNN. On the other hand, from the assumption we know that $A_{i}$ has a fixed value for every $i \neq j$. As a result, equation (46) is used to show that $q_{i}$ must have a fixed value for every $i \neq j$. Thus, equation (46) can be re-written as

$$
\begin{equation*}
0=-Y+Z\left((n-1) q_{i}+q_{j}\right)+\left(A_{i}+q_{i}\right) b . \tag{47}
\end{equation*}
$$

With a similar argument, we can show that $x_{i, s}$ also has the same value for every $i \neq j$. Equation (45), thus, can be represented as

$$
\begin{equation*}
0=\theta_{s}\left(-Y_{s}+Z\left((n-1) q_{i}+q_{j}+(n-1) x_{i, s}+x_{j, s}\right)+\frac{1}{R_{i}} x_{i, s}+b\left(A_{i}+q_{i}\right)\right) \tag{48}
\end{equation*}
$$

Solving equations (47) and (48), we find the values of $q_{i}$ and $x_{i, s}$ as functions of $q_{j}$ and $x_{j, s}$.

$$
\begin{align*}
q_{i} & =\frac{Y-b A_{i}-Z q_{j}}{b+(n-1) Z} \\
x_{i, s} & =-\frac{R_{i}\left(Y-Y_{s}+Z x_{j, s}\right)}{1+(n-1) Z R_{i}} \tag{49}
\end{align*}
$$

From (49) we can also calculate the values of $f$ and $p_{s}-f$ as functions of $q_{j}$ and $x_{j, s}$.

$$
\begin{align*}
f & =\frac{b\left(Y+(n-1) Z A_{i}-Z q_{j}\right)}{b+(n-1) Z} \\
p_{s}-f & =\frac{-Y+Y_{s}-Z x_{j, s}}{1+(n-1) Z R_{i}} \tag{50}
\end{align*}
$$

Inserting these values into the utility function from Lemma 5.2 simplifies the utility function to

$$
\begin{aligned}
u_{j}= & \left(\frac{b\left(Y+(n-1) Z A_{i}-Z q_{j}\right)}{b+(n-1) Z}-\alpha_{j}-\frac{\beta_{j}}{2} q_{j}\right) q_{j} \\
& +\sum_{s=1}^{S} \theta_{s}\left(\frac{-Y+Y_{s}-Z x_{j, s}}{1+(n-1) Z R_{i}}-\frac{\beta_{j}+\delta_{j}}{2} x_{j, s}\right) x_{j, s}
\end{aligned}
$$

As $Z, \alpha_{j}, \beta_{j}$, and $R_{i}$ have non-negative values, $u_{j}$ is a concave function of $q_{j}$ and $\boldsymbol{x}_{j}$. Therefore, ignoring the rest of the constraints, the optimal value of $q_{j}$ and $x_{j, s}$ can be found using first order conditions.

First order conditions for $q_{j}$ and $x_{j, s}$ gives

$$
\begin{align*}
q_{j}^{*} & =\frac{b Y+(n-1) b Z A_{i}-(b+(n-1) Z) \alpha_{j}}{2 b Z+(b+(n-1) Z) \beta_{j}}  \tag{51}\\
x_{j, s}^{*} & =\frac{Y_{s}-Y}{2 Z+\left(1+(n-1) Z R_{i}\right)\left(\beta_{j}+\delta_{j}\right)} . \tag{52}
\end{align*}
$$

Now we need to show that we can always find $A_{j}$ and $R_{j}$, so that this value is a feasible solution to WONN and yields $e_{j, s}=0$. To do so, we first calculate
$\frac{e_{j, s}}{\theta_{s}}-\sum_{w} e_{j, w}$ for all $s$. From (45), (46), and (51)

$$
\begin{align*}
\frac{e_{j, s}}{\theta_{s}}-\sum_{w=1}^{S} e_{j, w} & =Y-Y_{s}+\frac{x_{j, s}}{R_{j}}+Z\left((n-1) x_{i, s}+x_{j, s}\right) \\
& =\frac{\left(Y-Y_{s}\right)\left(-1+R_{j}\left(Z+\beta_{j}+\delta_{j}\right)+(n-1) Z R_{i}\left(-1+R_{j}\left(\beta_{j}+\delta_{j}\right)\right)\right)}{R_{j}\left(1+(n-1) Z R_{i}\right)\left(2 Z+\left(1+(n-1) Z R_{i}\right)\left(\beta_{j}+\delta_{j}\right)\right)} \tag{53}
\end{align*}
$$

It is always possible to choose $R_{j}$ as follows to ensure that $\frac{e_{j, s}}{\theta_{s}}-\sum_{w} e_{j, w}=0$. Note that this does not change either of production quantities or prices. This value of $R_{j}$ is

$$
R_{j}=\frac{1+(n-1) Z R_{i}}{Z+\left(1+(n-1) Z R_{i}\right)\left(\beta_{j}+\delta_{j}\right)}
$$

We can also choose $A_{j}$ so that $\sum_{w} e_{j, w}=0$ without changing any production quantity and thus any prices. From (46) and (49)

$$
\begin{align*}
\sum_{w=1}^{S} e_{j, w} & =-Y+Z\left((n-1) q_{i}+q_{j}\right)+b\left(A_{h}+q_{h}\right)  \tag{54}\\
& =-Y+b\left(A_{j}+q_{j}\right)+\frac{(n-1) Z\left(Y-b A_{i}\right)+b Z q_{j}}{b+(n-1) Z}
\end{align*}
$$

Solving $\sum_{w} e_{j, w}=0$ for $A_{j}$ gives

$$
\begin{aligned}
A_{j}= & \frac{-b Y(b+(n-2) Z)+(b+(n-1) Z)\left((b+n Z) \alpha_{j}+Y \beta_{j}\right)}{(b+(n-1) Z)\left(2 b Z+(b+(n-1) Z) \beta_{j}\right)} \\
& +\frac{-(n-1) Z A_{i}\left(b(b+(n-2) Z)-(b+(n-1) Z) \beta_{j}\right)}{(b+(n-1) Z)\left(2 b Z+(b+(n-1) Z) \beta_{j}\right)}
\end{aligned}
$$

These values of $A_{j}$ and $R_{j}$ ensure that $e_{j, s}=0 \forall s$. Thus, constraints [C6] and [C8] are met in WONN and RWNN.

From (51) we derive $\sum_{s} \theta_{s} x_{j, s}=0$. We can use the fact that $\sum_{s} \theta_{s} x_{j, s}=0$ to show that for $i \neq j$ also $\sum_{s} \theta_{s} x_{i, s}=0$ (in equation (49)). So this optimal point is feasible in [C1]. In sum, the constructed point is feasible for WONN, and gives an objective value at least as good as RWNN.

Now, we can use the above lemmas to prove a theorem that justifies using the equilibrium of the simplified game without the non-negativity constraints instead of the equilibrium of the original game.

Theorem. The equilibrium of the symmetric stochastic settlement game without the non- negativity constraints in ISOSP-FD is also the equilibrium of the stochastic settlement game with the non-negativity constraints.

Proof. To prove the theorem, we should show that if all generators offer the equilibrium values of $a_{i}$ and $d_{i}$, none of them are willing to deviate from it. Equivalently, if in WNN $a_{i}$ and $d_{i}$ are equal to the equilibrium of the SFSP game without the non-negativity constraints for all $i \neq j$, then optimal $a_{j}$ and $d_{j}$ are also equal to equilibrium values of this game.

The equilibrium of SFSP without non-negativity constraints is equal to the optimal value of WONN when every non-optimizer generator has offered the equilibrium values of the game. Thus, we prove that the optimal value of WONN is also optimal to WNN.

Firstly, Lemma 5.3 states that if the optimal solution to WONN is feasible to RWNN, then, it is also the optimal solution to RWNN. In our problem, from Proposition 8 we know that the optimal solution to WONN holds both $q_{i} \geq 0$ and $q_{i}+x_{i, s} \geq 0$. The other constraints of RWNN are shared between these two models. Thus, it is feasible and optimal in RWNN.

On the other hand, every feasible solution to WNN is feasible in RWNN. So, if this solution (which is the optimal solution to RWNN) is feasible to WNN, then it is also optimal to WNN. From Proposition 8, we know that $q_{i} \geq 0$ and $q_{i}+x_{i, s} \geq 0$ for all $i$, as it is the equilibrium of the game without non-negativity constraints. This means this point is feasible in [C8] and [C9]. On the other hand, we know that $e_{i, s}=0$ for all $i$, as it is the optimal solution to WONN. This shows it also holds [C7]. The other constraints are common and thus met. In sum, This point is feasible and therefore optimal to WNN.

Thus, no generator is willing to deviate from this point unilaterally, and this is the equilibrium of WNN.


[^0]:    ${ }^{1}$ Insofar as using these estimates to make an offer, the information is only useful up to gate closure as thereafter offers can not be changed. There is no capacity market in the NZEM, therefore it is necessary to lock in generation offers well ahead of time to avoid a situation where demand must be curtailed involuntarily.
    ${ }^{2}$ The current financial settlement in the NZEM is based on ex post prices that are computed with average demand over a period. Constrained on and off payments are used to ensure sufficient payment is made to the generators. However the Electricity Authority is now considering real-time pricing and is in consultation with the stakeholders.

